

Ogen: An Overlapping Grid Generator for Overture

William D. Henshaw ¹

CASC: Centre for Applied Scientific Computing²

Lawrence Livermore National Laboratory

Livermore, CA, 94551

henshaw@llnl.gov

<http://www.llnl.gov/casc/people/henshaw>

<http://www.llnl.gov/casc/Overture>

November 2, 2003

UCRL-MA-132237

Abstract:

We describe how to generate overlapping grids for use with Overture using the `ogen` program. The user must first generate Mappings to describe the geometry (a set of overlapping grids whose union covers the domain). The overlapping grid then is constructed using the `Ogen` grid generator. This latter step consists of determining how the different component grids interpolate from each other, and in removing grid points from holes in the domain, and removing unnecessary grid points in regions of excess overlap. This document includes a description of commands, presents a series of command files for generating various overlapping grids and describes the overlapping grid algorithm. The `ogen` program can also be used to build unstructured hybrid grids where the overlap is replaced by an unstructured grid.

Contents

1	Introduction	3
2	Commands	3
2.1	Commands for <code>ogen</code>	3
2.2	Commands when creating Mappings	3
3	Things you should know to make an overlapping grid	5
3.1	Boundary conditions	5
3.2	Share flag	6
3.3	Turning off the cutting of holes	6
3.4	Turning off interpolation between grids	6
3.5	Implicit versus explicit interpolation	6
4	Examples	8
4.1	Square	8
4.2	Stretched Annulus	9
4.3	Cylinder in a channel	10

¹This work was partially supported by grant N00014-95-F-0067 from the Office of Naval Research

²Management prefers the spelling 'Center'

4.4	Cylinder in a channel, cell-centered version	11
4.5	Cylinder in a channel, fourth-order version	12
4.6	Cylinder in a channel, multigrid version	13
4.7	Inlet-outlet	14
4.8	Valve	19
4.9	NACA airfoil	21
4.10	Hybrid grid for the inlet-outlet	23
4.11	Stretched cube	25
4.12	Sphere in a box	26
4.13	Sphere in a tube	28
4.14	Intersecting pipes	30
4.15	Body Of Revolution	32
4.16	3D valve	34
4.17	Adding new grids to an existing overlapping grid.	36
4.18	Incrementally adding grids to an overlapping grid.	37
4.19	Other sample command files and grids	39
5	Mixed physical-interpolation boundaries, making a c-grid, h-grid or block-block grid	47
5.1	Automatic mixed-boundary interpolation	47
5.2	Manual specification of mixed-boundary interpolation points	47
5.3	Spitting a grid for interpolation of a grid to itself	48
6	Manual Hole Cutting and Phantom Hole Cutting	51
7	Trouble Shooting	52
7.1	Failure of explicit interpolation	52
7.2	Tips	54
8	Adding user defined Mapping's	55
9	Overlapping Grid Generator: Ogen	57
9.1	Command descriptions	57
9.1.1	Interactive updateOverlap	57
9.1.2	Non-interactive updateOverlap	57
9.1.3	Moving Grid updateOverlap	57
9.2	Algorithm	59
9.3	Hole cutting algorithm	59
9.4	Finding exterior points by ray tracing	60
9.5	Adjusting grid points for the boundary mismatch problem	62
9.6	Refinement Grids	64
9.7	Improved Quality Interpolation	65
9.7.1	Note:	65
10	Treatment of nearby boundaries and the boundaryDiscretisationWidth	67
11	Adaptive Mesh Refinement	69
11.1	The algorithm for updating refinement meshes added to an overlapping grid.	69
11.2	Example: Circle in a Channel	71
11.3	Example: Valve	74

1 Introduction

The `ogen` program can be used to interactively generate overlapping grids.

The basic steps to follow when creating an overlapping grid are

- create mappings that cover a domain and overlap where they meet.
- generate the overlapping grid (`ogen` calls the grid generator `Ogen`).
- save the grid in a data-base file.

The `ogen` program is found in the `Overture/bin` directory. Just type `ogen` to get started. You can also type '`ogen noplot`' in which case `ogen` will run without graphics. This is useful if you just want to execute a command file to regenerate a grid – running without graphics is faster. If you have a command file, `example.cmd`, then you can type '`ogen example.cmd`' or '`ogen example`' (a `.cmd` will automatically be added) to run the commands in the file. To run without graphics type '`ogen noplot example`'.

Once you have made a grid and saved it in a data-base file (named `myGrid.hdf`, for example) you can look at it using the command `Overture/bin/plotStuff myGrid.hdf` (or just `Overture/bin/plotStuff myGrid`).

Figure 1 shows a snap-shot of `ogen` running.

Other documents of interest that are available through the Overture home page are

- Mapping class documentation : `mapping.tex`, [2]. Many of the mappings that are used to create an overlapping grid are documented here.
- Interactive plotting : `PlotStuff.tex`, [3].

2 Commands

2.1 Commands for `ogen`

The commands in the initial `ogen` menu are

create mappings : create mappings to represent the geometry. See section (2.2).

generate an overlapping grid : once mappings have been created an overlapping grid can be generated with this option. This will call the `Ogen` grid generator. See section (9.1) for a list of the commands available with the grid generator.

make an overlapping grid : this calls the old `Cgsh` grid generator, the original Overture grid generator.

save and overlapping grid : Save an overlapping grid in a data base file.

2.2 Commands when creating Mappings

The basic commands available from the `create mappings` menu option are (this list will in general be out of date so you are advised to run `ogen` to see the currently available options). Most of these commands simply create a new Mapping and call the update function for that Mapping. Descriptions of the **Mapping's** referred to here can be found in the mapping documentation [2].

help : output minimal help.

1D Mappings :

line : Build a line in 1D. This can be used for a 1D overlapping grid. Reference `LineMapping`.

stretching function : Reference `StretchMapping`.

spline (1D) : Reference `SplineMapping`.

2D Mappings :

Airfoil : Build a two-dimensional airfoil from various choices including the NACA 4 digit series airfoils. Reference `AirfoilMapping`.

Annulus : Reference `AnnulusMapping`.

Circle or ellipse : Reference CircleMapping.

DataPointMapping : Build a new Mapping from a set of discrete data points. The data points may be read from a plot3d file. Reference DataPointMapping.

line (2D) : Reference LineMapping.

nurbs (curve) : build a NURBS (a type of spline) curve or surface from control points or by interpolating data points. Reference NurbsMapping.

rectangle : Reference SquareMapping.

SmoothedPolygon : Build a grid or curve with a boundary that is a polygon with smoothed out corners. Reference SmoothedPolygonMapping.

spline : Reference SplineMapping.

tfi : Build a new Mapping from existing curves or surfaces using transfinite interpolation (Coon's patch). Reference TFIMapping.

3D Mappings :

Box : Reference BoxMapping.

Cylinder : Reference CylinderMapping.

Circle or ellipse (3D) : Reference CircleMapping.

CrossSection : Reference CrossSectionMapping.

DataPointMapping : Build a new Mapping from a set of discrete data points. The data points may be read from a plot3d file. Reference DataPointMapping.

line (3D) : Reference LineMapping.

nurbs (surface) : build a NURBS (a type of spline) curve or surface from control points or by interpolating data points. Reference NurbsMapping.

plane or rhombus : Reference PlaneMapping.

Sphere : Reference SphereMapping.

spline (3D) : Reference SplineMapping.

tfi : Build a new Mapping from existing curves or surfaces using transfinite interpolation (Coon's patch). Reference TFIMapping.

transform :

body of revolution : create a body of revolution from a two-dimensional Mapping. Reference RevolutionMapping.

elliptic : generate an elliptic grid on an existing grid in order to redistribute grid points. Reference EllipticTransform.

fillet : Build a fillet surface to join two intersecting surfaces. Reference FilletMapping.

hyperbolic : Reference HyperbolicMapping.

hyperbolic surface : Reference HyperbolicSurfaceMapping.

intersection : Determine the intersection curve between two intersecting surfaces. Reference IntersectionMapping.

mapping from normals : Generate a new Mapping by extending normals from a curve or a surface. Reference NormalMapping.

reparameterize : reparameterize an existing Mapping by

1. restricting the domain space to a sub-rectangle (this would be used to create an refinement patch on an adaptive grid)
2. remove a polar singularity by creating a new patch with an orthographic transform.

Reference ReparameterizationTransform, OrthographicTransform and RestrictionMapping.

rotate/scale/shift : transform an existing Mapping. Reference MatrixMapping.

stretch coordinates : stretch (cluster) the grid points in the coordinate directions. Reference `StretchTransform` and `StretchMapping`.

change :

change a mapping : Make changes to an existing Mapping.

copy a mapping : Make a copy of an existing Mapping.

delete a mapping : delete an existing Mapping.

data base :

open a data-base : open an Overture data-base file (new or old).

get from the data-base : read Mapping's from the data-base.

put to the data-base : save a Mapping in the data-base.

close the data-base : close the data-base.

save plot3d file : write a plot3d file.

read from file :

read plot3d file : read a plot3d formatted file and extract the grids. Each grid becomes a `DataPointMapping`.

read iges file : *experimental* read an IGES (Initial Graphics Exchange Specification) file such as created by pro/ENGINEER and build NURBS and trimmed NURBS found in the file.

read overlapping grid file : read an existing overlapping grid data base file and extract all the Mapping's from it. These Mappings can then be changed.

view mappings : view the currently defined Mappings.

check mapping : check a Mapping to see that it is defined properly. This is normally only done when one defines a new Mapping.

exit this menu :

3 Things you should know to make an overlapping grid

Here are some things that you will need to know when building overlapping grids. The examples that follow will demonstrate all of these ideas.

3.1 Boundary conditions

Each side of each component grid must be given a boundary condition value. These boundary conditions are essential since they indicate whether a boundary is a physical boundary (a value greater than 0), an interpolation boundary (a value equal to zero) or a side that has a periodic boundary condition (a value less than zero). The boundary condition values are stored in an array as

$$\text{boundaryCondition}(\text{side}, \text{axis}) = \begin{cases} > 0 & \text{physical boundary} \\ = 0 & \text{interpolation boundary} \\ < 0 & \text{periodic boundary} \end{cases}$$

`boundaryCondition(0,0) = left`

`boundaryCondition(1,0) = right`

`boundaryCondition(0,1) = bottom`

`boundaryCondition(1,1) = top`

`boundaryCondition(0,2) = front (3D)`

`boundaryCondition(1,2) = back (3D)`

where `side=0,1` and `axis=0,1` in 2D, or `axis=0,1,2` in 3D, indicates the face of the the grid. Note that each grid is a mapping from the unit square or unit cube to a physical domain – the terms left, right, bottom, top, front and back refer to the

sides of the unit square or cube. When you enter the boundary condition values (when changing them in a mapping) you should enter them in the order: left, right, bottom, top, front, back.

The grid generator uses physical boundaries to cut holes in other grids that happen to cross that physical boundary. See, for example, the “cylinder in a channel example” where the rectangular grid has a hole cut out of it. Interpolation boundaries are non-physical boundaries where the grid generator will attempt to interpolate the points from other component grids. A periodic boundary can be either be a branch cut (as on an annulus) or it can indicate a periodic domain (as with a square where the right edge of the square is to be identified with the left edge).

3.2 Share flag

The share flag is used to indicate when two different component grids share a common boundary (see the “inlet outlet” example, section (4.7)). The grid generator uses the share flag so that a boundary of one component grid will not accidentally cut a hole in another grid when the two grids are actually part of the same boundary. This could happen since, due to inaccuracies in representing each grid, it may seem that the boundary on one grid lies inside or outside the other grid (even though they are meant to be the same boundary curve).

The share flag is saved in an array that is the same shape as the `boundary condition` array

```
share(side,axis) > 0  a code that should be the same on all shared boundaries.
share(0,0) = left
share(1,0) = right
share(0,1) = bottom
share(1,1) = top
share(0,2) = front (3D)
share(1,2) = back (3D)
```

where `side=0,1` and `axis=0,1` in 2D, or `axis=0,1,2` in 3D, indicates the face of the the grid.

Thus the share flags on all grid faces that belong to the same boundary should be given the same share value. This could be accomplished by setting all share values to 1 say, although this is slightly dangerous as the grid generator could make a mistake. It is better to use a different positive integer for each different boundary.

3.3 Turning off the cutting of holes

By default, the overlapping grid generator will use any physical boundary (a side of a grid with a positive `boundaryCondition`) to try and cut holes in any other grid that lies near the physical boundary. Thus in the “cylinder in a channel example” section (4.3) the inner boundary of the annulus cuts a hole in the rectangular grid. Sometimes, as in the “inlet outlet” example, section (4.7), one does not want this to happen. In this case it is necessary to explicitly specify which grids are allowed to cut holes in which other grids. This can be done through in the `change parameters` option with the `prevent hole cutting` option, see section the “inlet outlet” example, (4.7).

3.4 Turning off interpolation between grids

By default all grids can interpolate from all other grids. This default can be changed and you may specify which grids may interpolate from which other grids. This option can be used, for example, to build grids for two disjoint domains that match along a boundary as shown in figure (22).

3.5 Implicit versus explicit interpolation

There are two types of interpolation, **explicit** and **implicit**. **Explicit** interpolation means that a point that is interpolated will only use values on other grids that are not interpolation points themselves. This means that will the default 3 point interpolation the amount of overlap must be at least 1.5 grid cells wide. With explicit interpolation the interpolation equations can be solved explicitly (and this faster).

With **implicit** interpolation the points used in the interpolation stencil may themselves be interpolation points. This means that will the default 3 point interpolation the amount of overlap must be at least .5 grid cells wide. Thus **implicit interpolation is more likely to give a valid grid** since it requires less overlap. With implicit interpolation the interpolation equations are a coupled system that must be solved. This is a bit slower but the `Overture` interpolation function handles this automatically.

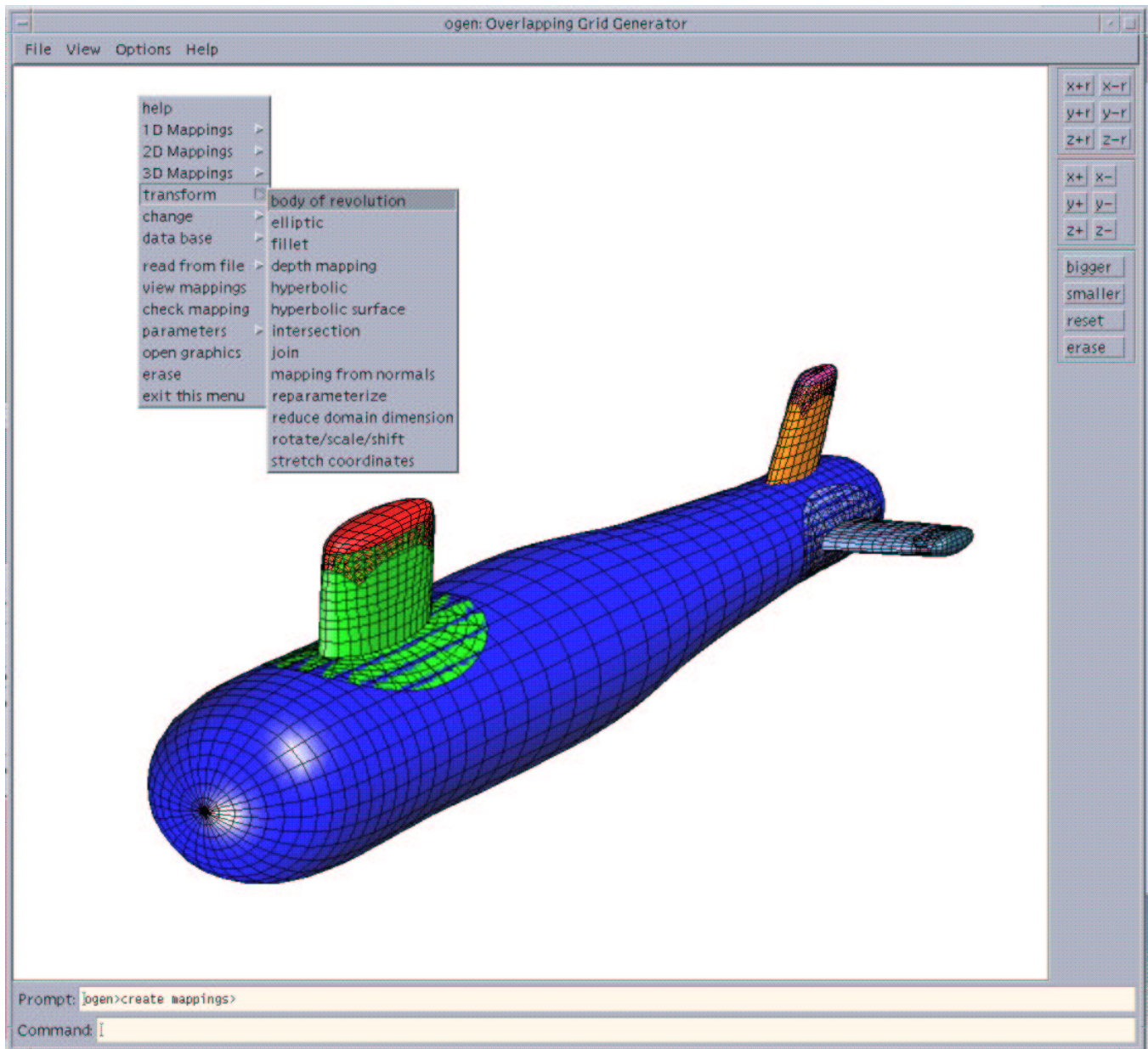


Figure 1: A snapshot of ogen

4 Examples

In this section we describe a number of *command files* that can be used to create various overlapping grids. During an interactive session a command file can be saved, see the option `'log commands to file'` in the file pull-down menu. By default the command file `ogen.cmd` is automatically saved. The command file will record all the commands that are issued. The command file can be later read in, using `'read command file'` in the file pull-down menu, and the commands will be executed. You can also type `'ogen example.cmd'` to run the command file named `example.cmd` with graphics or `'ogen noplot example.cmd'` to run without graphics.

The command file can be edited and changed. Once a complicated grid has been created it is usually easiest to make minor changes by editing the command file. The pause command can be added to the command file which will cause the program to pause at that point and wait for an interactive response – one can then either continue or break.

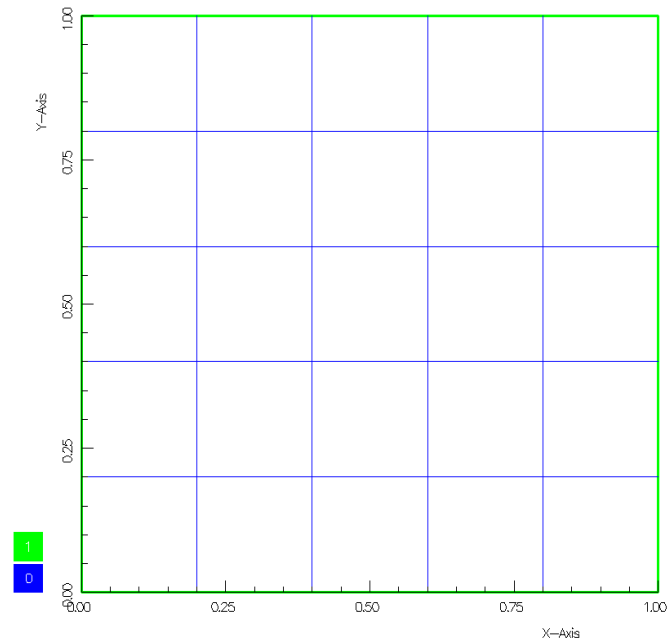
4.1 Square

Here is a command file to create a square. (file `Overture/sampleGrids/square5.cmd`) We first make a mapping for the square and assign various parameters such as the number of grid points and the boundary conditions. Any positive number for the boundary condition indicates a physical boundary. Next the overlapping grid generator is called (`make an overlapping grid`) to make an overlapping grid (which is trivial in this case). Finally the overlapping grid is saved in a data-base file. The data-base file is an HDF formatted file. HDF is the Hierarchical Data Format (HDF) from the National Centre for Super-Computing Applications (NCSA). You can look at the data base file created here by typing `plotStuff square5.hdf` (or just `plotStuff square5`) where `plotStuff` is found in `Overture/bin`.

```

1  * make a simple square
2  create mappings
3    rectangle
4    mappingName
5    square
6    lines
7    6 6
8    boundary conditions
9    1 1 1 1
10  exit
11  exit
12  *
13  generate an overlapping grid
14    square
15    done
16    change parameters
17    ghost points
18    all
19    2 2 2 2 2 2
20  exit
21  compute overlap
22  exit
23  *
24  save an overlapping grid
25    square5.hdf
26    square5
27  exit

```



An “overlapping grid” that is just a square

4.2 Stretched Annulus

FAQ : What the heck is going on with the stretching function?! (F. Olsson-Hector)

Answer: Here is a command file to create an annulus with stretching. (file Over-ture/sampleGrids/stretchedAnnulus.cmd) Grid lines can be stretched in the coordinate directions (i.e. in the unit-square coordinates). When grid lines are stretched, as in the example below, the graphics screen will show one of the following

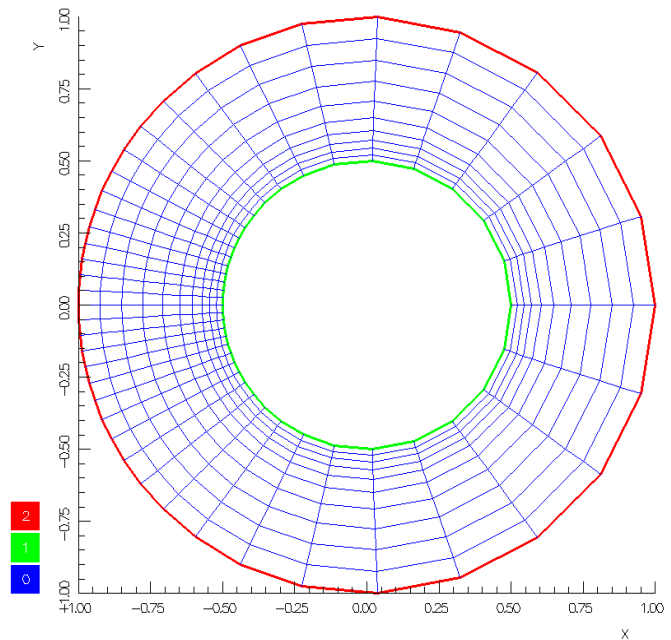
- The mapping to be stretched (annulus)
- The unit square to be stretched.
- The one dimensional stretching function.

The stretching functions are described in the documentation on Mapping's [2].

```

1  *
2  * Create an annulus and stretch the grid lines
3  *
4  create mappings
5  * create an Annulus
6  Annulus
7  lines
8  41 11
9  exit
10 * stretch the grid lines
11 stretch coordinates
12   transform which mapping?
13   Annulus
14   stretch
15   specify stretching along axis=0
16 * choose a layer stretching  $a*\tanh(b*(r-c)$ 
17   layers
18   1
19 *   give a,b,c in above formula
20   1. 10. .5
21   exit
22   specify stretching along axis=1
23   layers
24   1
25   1. 5. 0.
26   exit
27   exit
28   exit
29 exit this menu
30 *
31 * make an overlapping grid
32 *
33 generate an overlapping grid
34 stretched-Annulus
35 done
36 compute overlap
37 exit
38 *
39 * save as an hdf file
40 *
41 save an overlapping grid
42 stretchedAnnulus.hdf
43 grid
44 exit

```



An annulus with stretching

For the pundits: The stretched annulus is a `StretchTransform Mapping` which is a composition of the `Stretched-Square Mapping` and the `Annulus Mapping`. The `StretchedSquare` uses the `Stretch Mapping` where the actual one dimensional stretching functions are defined.

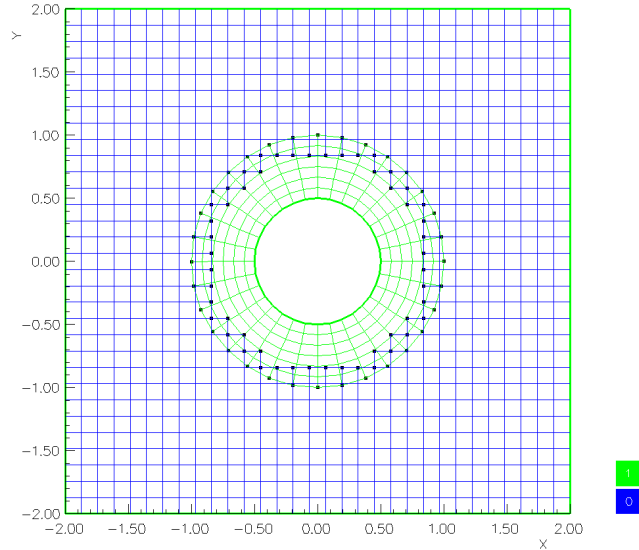
4.3 Cylinder in a channel

Here is a command file to create a cylinder in a channel. (file Overture/sampleGrids/cic.cmd) In this case we make two mappings, one a background grid and one an annulus. The boundary conditions on the annulus are set so that the outer boundary is an interpolation boundary (=0) while the boundary conditions on the branch cut are -1 to indicate a periodic boundary. We show two overlapping grids, one made with implicit interpolation (default) and one made with explicit interpolation. The latter has a bigger region of overlap.

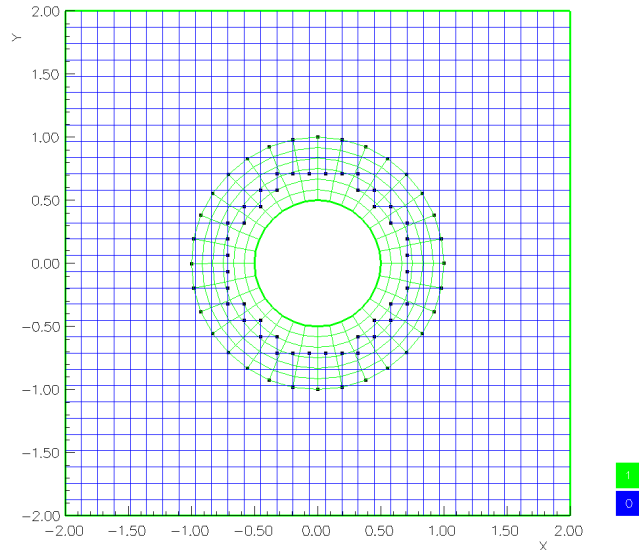
```

1  *
2  * circle in a channel
3  *
4  create mappings
5  *
6  rectangle
7    set corners
8    -2. 2. -2. 2.
9    lines
10   32 32
11   boundary conditions
12   1 1 1 1
13   mappingName
14   square
15 exit
16 *
17 Annulus
18   lines
19   33 7
20 *   centre
21 *   0. 1.
22   boundary conditions
23   -1 -1 1 0
24 exit
25 *
26 exit
27 generate an overlapping grid
28   square
29   Annulus
30 done
31 change parameters
32 * choose implicit or explicit interpolati
33 * interpolation type
34 *   implicit for all grids
35 ghost points
36   all
37   2 2 2 2 2 2
38 exit
39 * display intermediate results
40 compute overlap
41 exit
42 *
43 save an overlapping grid
44 cic.hdf
45 cic
46 exit
47

```



An overlapping grid for a cylinder in a channel with implicit interpolation



An overlapping grid for a cylinder in a channel with explicit interpolation

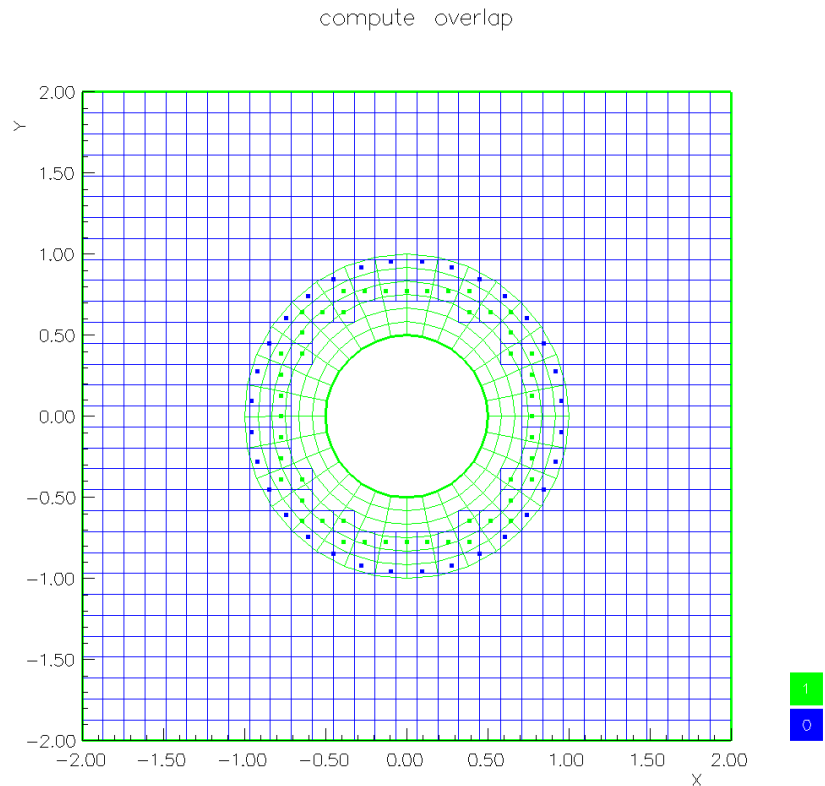
4.4 Cylinder in a channel, cell-centered version

Here we repeat the last example but create a cell-centered grid. In a cell-centered grid the cell-centres of one grid are interpolated from the cell-centres of another grid. For this reason the cell-centered grid requires slightly more overlap between the component grids.

```

1  *
2  * circle in a channel, cell centered grid
3  *
4  create mappings
5  *
6  rectangle
7  set corners
8  -2. 2. -2. 2.
9  lines
10 32 32
11 boundary conditions
12 1 1 1 1
13 mappingName
14 square
15 exit
16 *
17 Annulus
18 lines
19 33 7
20 boundary conditions
21 -1 -1 1 0
22 exit
23 *
24 exit
25 generate an overlapping grid
26 square
27 Annulus
28 done
29 change parameters
30 * make the grid cell-centered
31 cell centering
32 cell centered for all grids
33 exit
34 compute overlap
35 exit
36 *
37 save an overlapping grid
38 cicCC.hdf
39 cicCC
40 exit
41

```



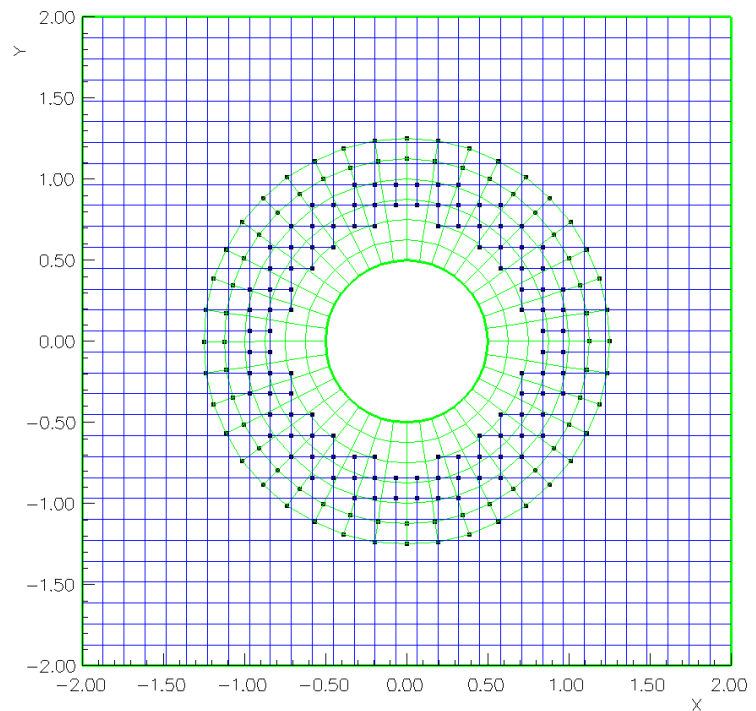
An overlapping grid for a cylinder in a channel, cell-centered case.

4.5 Cylinder in a channel, fourth-order version

Here we repeat the last example but create a grid appropriate for a fourth-order discretization. We need to increase the discretization width to 5 and the interpolation width to 5. This can either be done explicitly or the option “order of accuracy” can be used. Notice that two lines of interpolation points are generated as required by the wider stencil.

```

1  *
2  * circle in a channel, for fourth order accuracy. This
3  * can be used with primer/wave
4  *
5  create mappings
6  *
7  rectangle
8    set corners
9      -2. 2. -2. 2.
10   lines
11     129 129
12   boundary conditions
13     1 1 1 1
14   mappingName
15     square
16 exit
17 *
18 Annulus
19   lines
20     161 9
21   outer radius
22     .75
23   boundary conditions
24     -1 -1 1 0
25 exit
26 *
27 exit
28 generate an overlapping grid
29   square
30   Annulus
31   done
32   change parameters
33     * choose implicit or explicit intergr
34     interpolation type
35       implicit for all grids
36     * explicit for all grids
37   ghost points
38     all
39     2 2 2 2
40   order of accuracy
41     fourth order
42 *   we could also do the following:
43 *     discretization width
44 *       all
45 *       5 5
46 *     interpolation width
47 *       all
48 *       all
49 *       5 5
50 exit
51 compute overlap
52 exit
53 *
54 save an overlapping grid
55 cic.4.hdf
56 cic4
57 exit
58
```



An overlapping grid for a cylinder in a channel, fourth-order case.

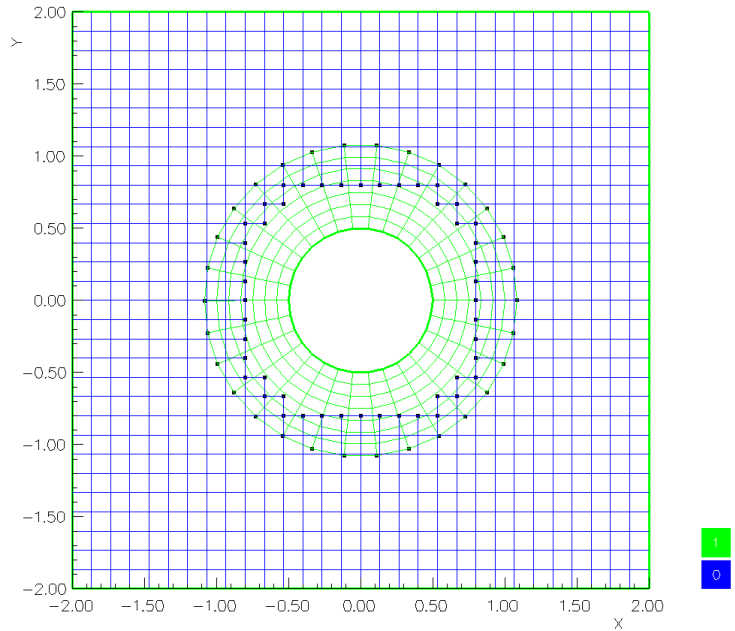
4.6 Cylinder in a channel, multigrid version

Here we make a grid that can be used with a multigrid solver. The only difference in the command file is that we must specify how many multigrid levels we require. **NOTE** that since each multigrid level must be a valid overlapping grid you cannot expect to have more than a few levels. See the examples in the primer for how to access the different multigrid levels in a CompositeGrid.

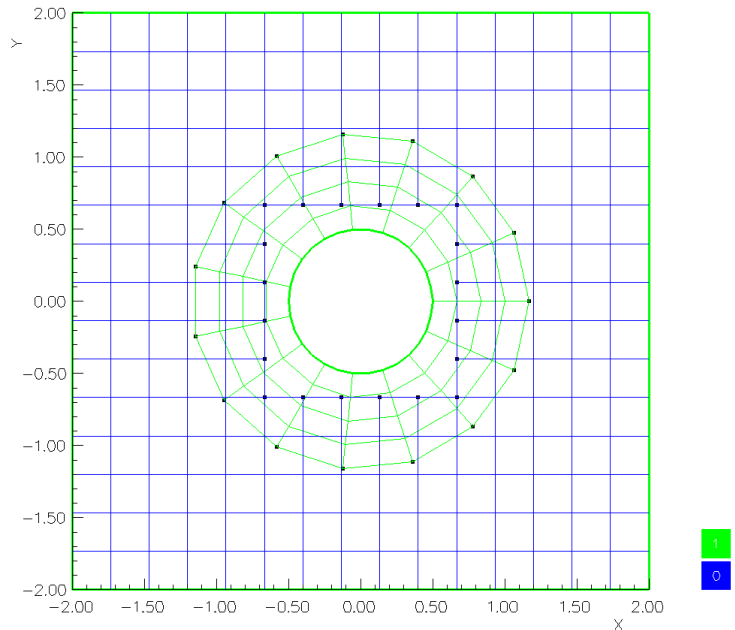
```

1  *
2  * circle in a channel with MG levels
3  *
4  create mappings
5  *
6  rectangle
7    set corners
8      -2. 2. -2. 2.
9    lines
10     45 45
11    boundary conditions
12     1 1 1 1
13    mappingName
14    square
15  exit
16  *
17  Annulus
18    lines
19     65 9
20    boundary conditions
21     -1 -1 1 0
22  exit
23  *
24  exit
25  generate an overlapping grid
26    specify number of multigrid levels
27    2
28    square
29    Annulus
30    done
31    change parameters
32      interpolation type
33        explicit for all grids
34      ghost points
35        all
36        2 2 2 2 2 2
37    exit
38    * pause
39    compute overlap
40  exit
41  save an overlapping grid
42  cicmg.hdf
43  cic
44  exit

```



An overlapping grid for a cylinder in a channel, multigrid level 0.



An overlapping grid for a cylinder in a channel, multigrid level 1.

4.7 Inlet-outlet

In this example we demonstrate

share flags: to specify that two component grids have sides that belong to the same physical boundary curve. This prevents one physical boundary from accidentally cutting a hole on a grid that shares the same boundary.

no hole cutting: turn off hole cutting to prevent physical boundaries from cutting holes in some other grids.

view mappings: the mappings can be plotted with boundaries coloured by the boundary condition values or coloured by the share flag values. This allows one to check that the values have been set properly.

This grid is remarkably similar to a grid created by Anders Petersson.

Here is a command file to create the grid for the inlet-outlet example. (file `Over-ture/sampleGrids/inletOutlet.cmd`).

```

1  *
2  * create a grid to demonstrate various features
3  *
4  create mappings
5  * make a back ground grid
6  rectangle
7  set corners
8  0 2. 0 1.
9  lines
10 61 31
11 mappingName
12 backGroundGrid
13 share
14 1 2 3 4
15 exit
16 * make an annulus
17 Annulus
18 centre for annulus
19 1. .5
20 inner radius
21 .2
22 outer radius
23 .4
24 lines
25 41 9
26 mappingName
27 annulus
28 boundary conditions
29 -1 -1 1 0
30 exit
31 * the inlet (on the right) will consist of two
32 * smoothed polygons
33 SmoothedPolygon
34 mappingName
35 inlet-top
36 vertices
37 3
38 2. .85
39 2. .65
40 2.25 .65
41 n-dist
42 fixed normal distance
43 -.175 .2
44 sharpness
45 10.
46 10.
47 10.
48 t-stretch
49 0. 10.
50 1. 10.
51 0. 10.
52 lines
53 25 11
54 boundary conditions
55 0 1 1 0
56 * One boundary here should match one boundary of
57 * the backGroundGrid, while another boundary
58 * should match a boundary on the inlet-bottom.
59 * Set share flag to match corresponding share values
60 share
61 0 5 2 0
62 exit
63 *
64 SmoothedPolygon
65 mappingName
66 inlet-bottom
67 vertices
68 3
69 2. .15
70 2. .35
71 2.25 .35
72 lines
73 25 11
74 n-dist
75 fixed normal distance
76 .175 .2
77 sharpness
78 10.
79 10.
80 10.
81 t-stretch
82 0. 10.
83 1. 10.
84 0. 10.
85 boundary conditions
86 0 1 1 0
87 * One boundary here should match one boundary
88 * of the backGroundGrid, while another boundary
89 * should match a bounbdary on the inlet-bottom.
90 * Set share flag to match corresponding share values
91 share
92 0 5 2 0
93 exit
94 * here is an outlet grid made in the poor man's way
95 rectangle
96 set corners
97 -.35 .05 .3 .7
98 lines
99 15 15
100 mappingName
101 outlet
102 boundary conditions
103 1 0 1 1
104 exit
105 * now look at the mappings
106 view mappings
107 backGroundGrid
108 annulus

```

```

109      inlet-top
110      inlet-bottom
111      outlet
112      *
113      * The grid is plotted with boundaries coloured
114      * by the boundary condition number. Here we
115      * should check that all interpolation boundaries
116      * are 0 (blue), all physical boundaries are positive
117      * and periodic boundaries are black
118      * pause
119      *
120      * now we plot the boundaries by share value
121      * The sides that correspond to the same boundary
122      * should be the same colour
123      colour boundaries by share value
124      * pause
125      erase and exit
126      exit
127      generate an overlapping grid
128      * put the nonconforming grid first to be a lower
129      * priority than the back-ground
130      outlet
131      backGroundGrid
132      annulus
133      inlet-top
134      inlet-bottom
135      done
136      change parameters
137      prevent hole cutting
138      backGroundGrid
139      all
140      outlet
141      all
142      done
143      ghost points
144      all
145      2 2 2 2 2 2
146      exit
147      * display intermediate
148      * set debug parameter
149      * 31
150      compute overlap
151      exit
152      *
153      save an overlapping grid
154      inletOutlet.hdf
155      inletOutlet
156      exit
157

```

The cell-centred version may be created with `Overture/sampleGrids/inletOutlet.cmd`.

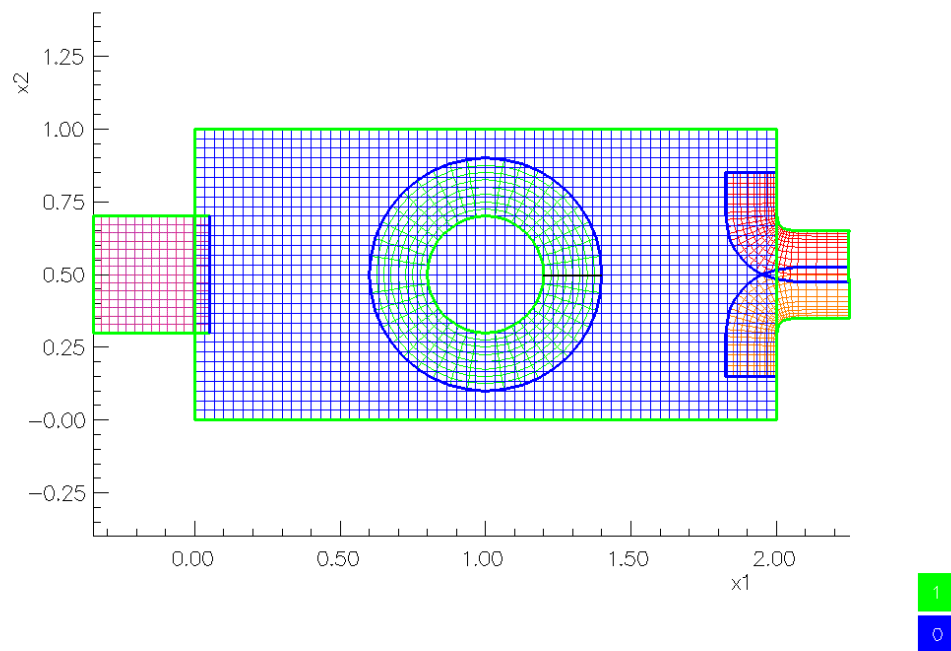


Figure 2: Inlet-outlet mappings plotted from the “view mappings” menu, showing boundary condition values. Physical boundaries have a positive value (1=green), interpolation boundaries have a value of zero (0=blue) and periodic boundaries have a negative value (shown in black).

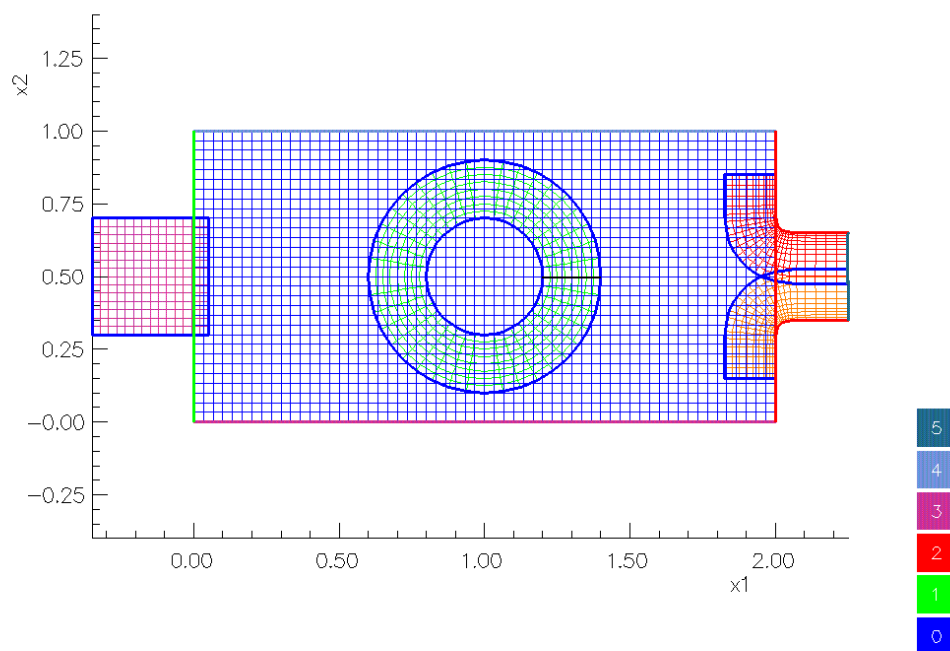


Figure 3: Inlet-outlet mappings plotted from the “view mappings” menu, showing shared side values. Grids that share the same physical boundary should have the same value of the share flag. For example, the two inlet grids on the right share boundaries with the back-ground grid (value 2=red). The inlet grids also share boundaries with each other (value 5)

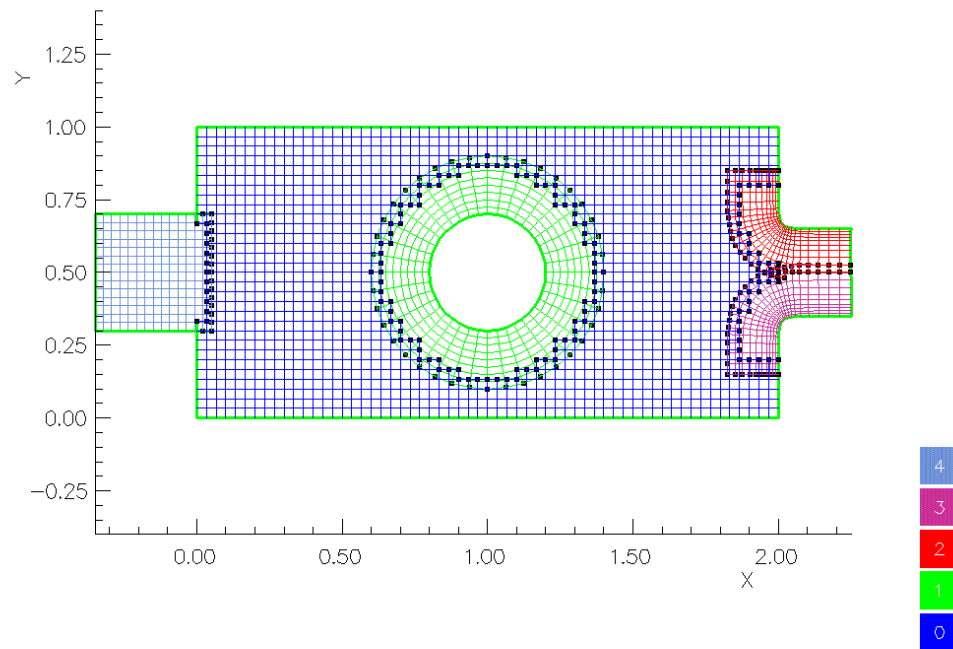


Figure 4: Inlet-outlet overlapping grid. To create this grid we had to prevent the background grid from cutting holes in the two inlet grids (on the right) and the outlet grid on the left. The outlet grid was also prevented from cutting holes in the background grid.

4.8 Valve

Here is a command file to create a grid around a two-dimensional valve (file Overture/sampleGrids/valve.cmd).

```

1  *
2  * Create an overlapping grid for a 2D valve
3  *
4  * time to make: old:27s (ultra) new: 4.4s
5  *
6  create mappings
7  *
8  * First make a back-ground grid
9  *
10 rectangle
11     mappingName
12     backGround
13     set corners
14         0 1. 0 1.
15     lines
16         * 41 41
17         * 51 51
18         49 49
19     share
20         1 2 3 4
21 exit
22 *
23 * Now make the valve
24 *
25 SmoothedPolygon
26     mappingName
27     valve
28     vertices
29         * .4 .4 .65 .65 ok
30         * .45 .45 .7 .7 ok
31         * .47 .47 .72 .72 ok
32         * .475 .475 .725 .725 no
33         * .47 .47 .72 .72 last used, ok
34         4
35         0.47 0.
36         0.47 .75
37         0.72 .5
38         0.72 0.
39     n-dist
40         fixed normal distance
41         * .1
42         .05
43     lines
44         * 65 9
45         * 75 9
46         73 9
47     boundary conditions
48         1 1 1 0
49     share
50         3 3 0 0
51     sharpness
52         15
53         15
54         15
55         15
56     t-stretch
57         1. 0.
58         1. 6.
59         1. 4.
60         1. 0.
61     n-stretch
62         1. 4. 0.
63     exit
64 *
65 * Here is the part of the boundary that
66 * the valve closes against
67 *
68 SmoothedPolygon
69     mappingName
70     stopper
71     vertices
72         4
73         1. .5
74         0.75 .5
75         0.5 .75
76         0.5 1.
77     n-dist
78         fixed normal distance
79         * .1
80         .05
81     lines
82         * 61 9
83         * 61 9
84         65 9
85     t-stretch
86         1. 0.
87         1. 5.
88         1. 5.
89         1. 0.
90     n-stretch
91         1. 4. 0.
92     boundary conditions
93         1 1 1 0
94     share
95         2 4 0 0
96     exit
97 exit
98 *
99 * Make the overlapping grid
100 *
101 generate an overlapping grid
102     backGround
103     stopper
104     valve
105     done
106     change parameters
107     ghost points
108     all
109     2 2 2 2 2 2
110     exit
111 * debug
112 * 7
113 * display intermediate results
114     compute overlap
115 * pause
116     exit
117 *
118 * save an overlapping grid
119     save a grid (compressed)
120     valve.hdf
121     valve
122     exit
123

```

The resulting grid is shown in figure 5. The cell centered version may be created with Overture/sampleGrids/valveCC.cmd.



Figure 5: An overlapping grid for a valve

4.9 NACA airfoil

Here is a command file to create a grid around a two-dimensional NACA0012 airfoil (file Overture/sampleGrids-/naca0012.cmd). The airfoil curve is created first with the AirfoilMapping (see the Mapping documentation for an explanation of NACA 4 digit airfoils). This curve is blended with an ellipse (using transfinite interpolation) to make an initial grid. The transfinite interpolation mapping then smoothed using elliptic grid generation to form the airfoil grid.

```

1  *
2  * Make a grid around a NACA0012 airfoil
3  *
4  create mappings
5  *
6  * First make a back-ground grid
7  *
8  rectangle
9  mappingName
10  backGround
11  set corners
12  -1.5 2.5 -1.5 1.5
13  lines
14  41 33 41 31
15  exit
16  * make the NACA0012 airfoil (curve)
17  Airfoil
18  airfoil type
19  naca
20  exit
21  * make an ellipse as an outer boundary
22  Circle or ellipse
23  specify centre
24  .5 .0
25  specify axes of the ellipse
26  1.5 1.
27  exit
28  * blend the airfoil to the ellipse to make a grid
29  tfi
30  choose bottom curve
31  airfoil
32  choose top curve
33  circle
34  boundary conditions
35  -1 -1 1 0
36  lines
37  73 17
38  mappingName
39  airfoil-tfi
40  * pause
41  exit
42  *
43  elliptic
44  *project onto original mapping (toggle)
45  transform which mapping?
46  airfoil-tfi
47  elliptic smoothing
48  * slow start to avoid problems at trailing edge
49  number of multigrid levels
50  3
51  maximum number of iterations
52  15
53  red black
54  smoother relaxation coefficient
55  .1
56  generate grid
57  * now reset parameters for better convergence
58  maximum number of iterations
59  30
60  smoother relaxation coefficient
61  .8
62  generate grid
63  exit
64  mappingName
65  airfoil-grid
66  * pause
67  exit
68  exit
69  *
70  * make an overlapping grid
71  *
72  generate an overlapping grid
73  backGround
74  airfoil-grid
75  done
76  change parameters
77  ghost points
78  all
79  2 2 2 2 2
80  exit
81  compute overlap
82  exit
83  *
84  save an overlapping grid
85  naca0012.hdf
86  naca
87  exit
88
89

```

The resulting grid is shown in figure 6.

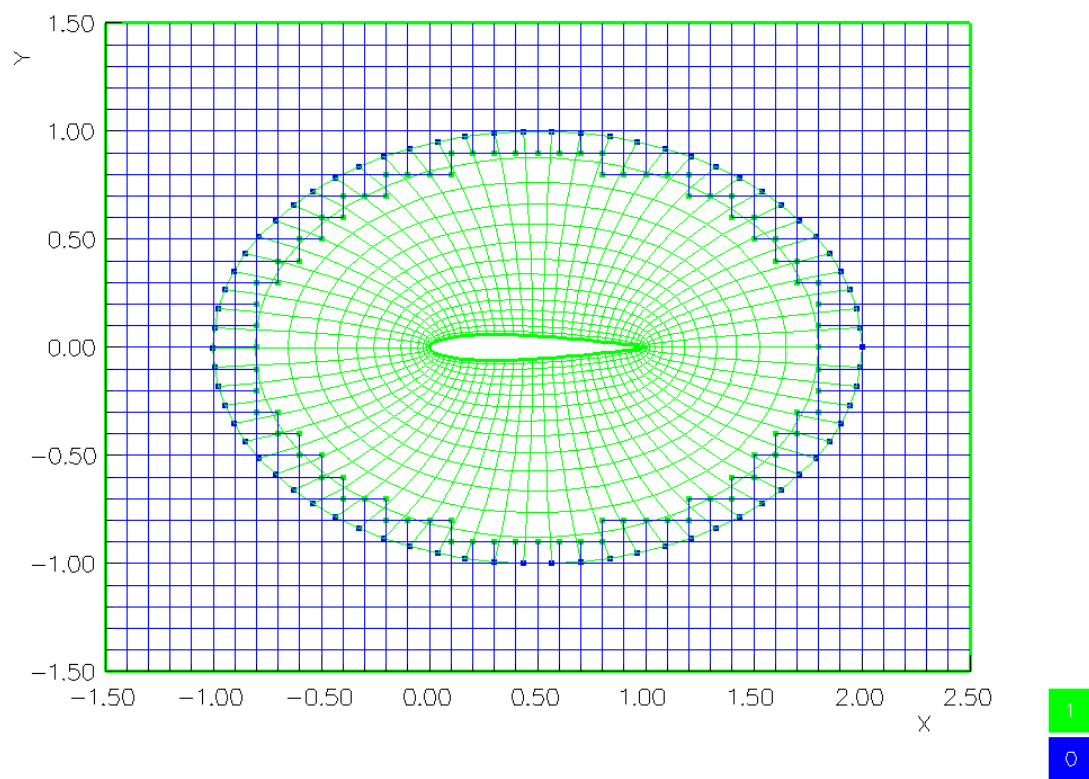


Figure 6: An overlapping grid for a NACA0012 airfoil

4.10 Hybrid grid for the inlet-outlet

Here is a command file to create a hybrid for an inlet-outlet geometry. Overture/sampleGrids-
/inletOutlet.hyb.cmd).

```

1  *
2  * create a grid to demonstrate various features
3  *
4  create mappings
5  * make a back ground grid
6  rectangle
7  set corners
8  0 2. 0 1.
9  lines
10 61 31
11 mappingName
12 backGroundGrid
13 share
14 1 2 3 4
15 exit
16 * make an annulus
17 Annulus
18 centre for annulus
19 1. .5
20 inner radius
21 .2
22 outer radius
23 .4
24 lines
25 41 9
26 mappingName
27 annulus
28 boundary conditions
29 -1 -1 1 0
30 exit
31 * the inlet (on the right) will consist of two
32 * smoothed polygons
33 SmoothedPolygon
34 mappingName
35 inlet-top
36 vertices
37 3
38 2. .85
39 2. .65
40 2.25 .65
41 n-dist
42 fixed normal distance
43 -.175 .2
44 sharpness
45 10.
46 10.
47 10.
48 t-stretch
49 0. 10.
50 1. 10.
51 0. 10.
52 lines
53 25 11
54 boundary conditions
55 0 1 1 0
56 * One boundary here should match one boundary
57 * the backGroundGrid, while another boundary
58 * should match a boundary on the inlet-bottom.
59 * Set share flag to match corresponding share values
60 share
61 0 5 2 0
62 exit
63 *
64 SmoothedPolygon
65 mappingName
66 inlet-bottom
67 vertices
68 3
69 2. .15
70 2. .35
71 2.25 .35
72 lines
73 25 11
74 n-dist
75 fixed normal distance
76 .175 .2
77 sharpness
78 10.
79 10.
80 10.
81 t-stretch
82 0. 10.
83 1. 10.
84 0. 10.
85 boundary conditions
86 0 1 1 0
87 * One boundary here should match one boundary
88 * of the backGroundGrid, while another boundary
89 * should match a boundary on the inlet-bottom.
90 * Set share flag to match corresponding share values
91 share
92 0 5 2 0
93 exit
94 * here is an outlet grid made in the poor man's way
95 rectangle
96 set corners
97 -.35 .05 .3 .7
98 lines
99 15 15
100 mappingName
101 outlet
102 boundary conditions
103 1 0 1 1
104 exit
105 * now look at the mappings
106 view mappings
107 backGroundGrid
108 annulus
109 inlet-top
110 inlet-bottom
111 outlet
112 *
113 * The grid is plotted with boundaries coloured
114 * by the boundary condition number. Here we
115 * should check that all interpolation boundaries
116 * are 0 (blue), all physical boundaries are positive
117 * and periodic boundaries are black
118 * pause
119 *
120 * now we plot the boundaries by share value
121 * The sides that correspond to the same boundary
122 * should be the same colour
123 colour boundaries by share value
124 pause
125 erase and exit
126 exit
127 generate a hybrid mesh
128 * put the nonconforming grid first to be a lower
129 * priority than the back-ground
130 outlet
131 backGroundGrid
132 annulus

```

```

133     inlet-top
134     inlet-bottom
135 done
136 change parameters
137     prevent hole cutting
138     backGroundGrid
139     all
140     outlet
141     all
142 done
143 exit
144 * display intermediate
145 * set debug parameter

146 * 31
147 compute overlap
148 exit
149 set plotting frequency (<1 for never)
150 -1
151 continue generation
152 exit
153 save grid in ingrid format
154 inletOutlet.hyb.msh
155 exit
156 *
157

```

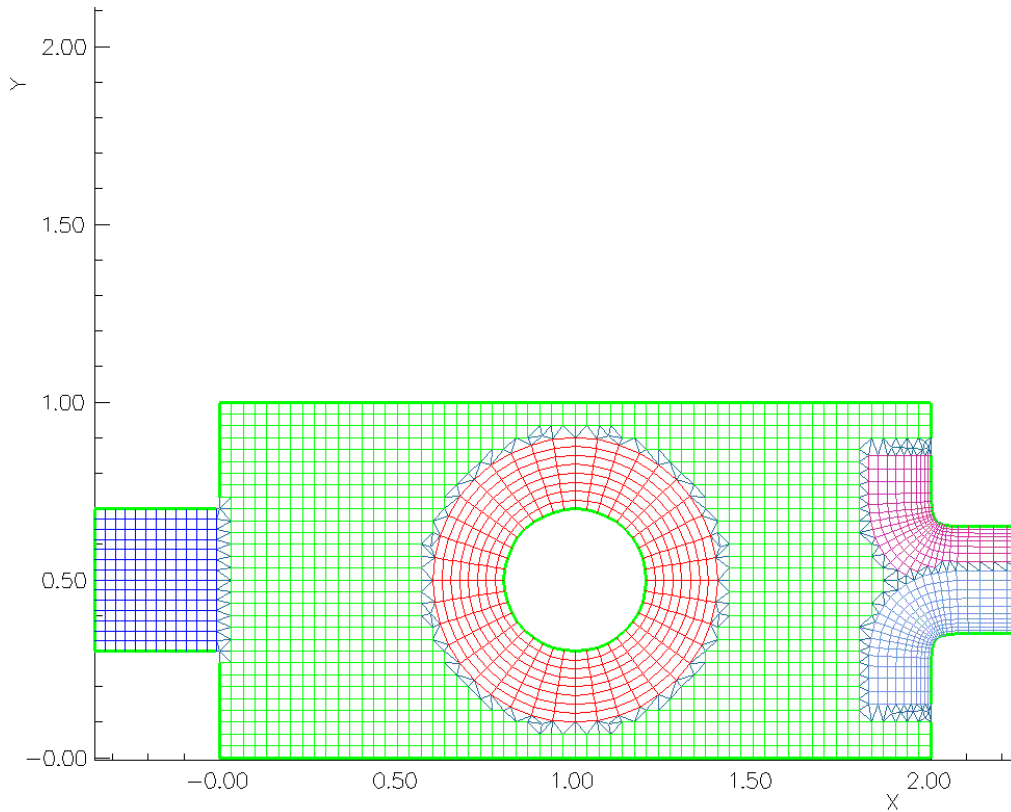


Figure 7: A hybrid grid for an inlet-outlet geometry.

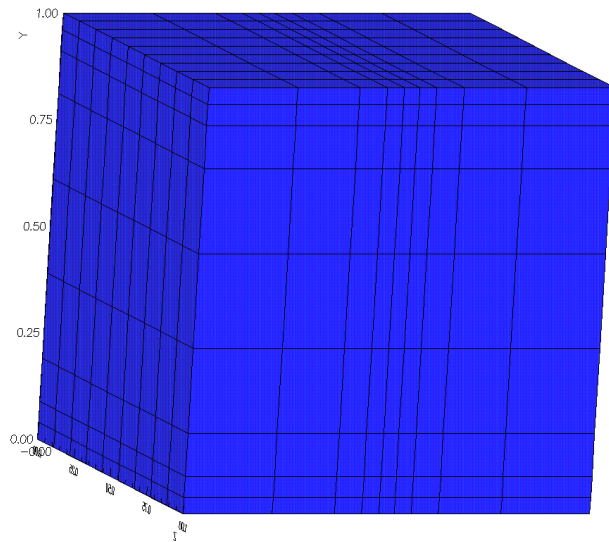
4.11 Stretched cube

Here is a command file to create a simple box in 3D with stretched grid lines. (file Overture/sampleGrids/-stretchedCube.cmd)

```

1  *
2  * Create a 3D cube with stretched grid lines
3  *
4  create mappings
5      Box
6      exit
7      stretch coordinates
8      stretch
9  *   choose a layer stretching  $a \tanh(b \cdot (r -$ 
10 *   along axis 0
11     specify stretching along axis=0 (x1)
12     layers
13     1
14 *   give a,b,c in above formula
15     1. 10. .5
16     exit
17 *   choose a stretching function with 2
18 *   layers along axis1
19     specify stretching along axis=1 (x2)
20     layers
21     2
22 *   give a,b,c for layer 1
23     1. 10. 0.
24 *   give a,b,c for layer 2
25     1. 10. 1.
26     exit
27     exit
28     exit
29 exit this menu
30 generate an overlapping grid
31     stretched-box
32     done
33     compute overlap
34 exit
35 save an overlapping grid
36     stretchedCube.hdf
37     stretchedCube
38 exit

```



An overlapping grid for a stretched cube.

4.12 Sphere in a box

Here is a command file to create a sphere in a box. The sphere is covered with two orthographic patches, one for the north-pole and one for the south-pole. (file Overture/sampleGrids/sib.cmd)

```

1  *
2  * command file to create a sphere in a box
3  *
4  *   time to make: 594s new: 3.5
5  *   cpu=2s (ovl5 sun-ultra optimized)
6  *   =.37 (tux50)
7  create mappings
8  * first make a sphere
9  Sphere
10 exit
11 *
12 * now make a mapping for the north pole
13 *
14 reparameterize
15   orthographic
16   specify sa,sb
17   2.5 2.5
18   exit
19   lines
20   15 15 5
21   boundary conditions
22   0 0 0 0 1 0
23   share
24   0 0 0 0 1 0
25   mappingName
26   north-pole
27 exit
28 *
29 * now make a mapping for the south pole
30 *
31 reparameterize
32   orthographic
33   choose north or south pole
34   -1
35   specify sa,sb
36   2.5 2.5
37   exit
38   lines
39   15 15 5
40   boundary conditions
41   0 0 0 0 1 0
42   share
43   0 0 0 0 1 0
44   mappingName
45   south-pole
46 exit
47 *
48 * Here is the box
49 *
50 Box
51   set corners
52   -2 2 -2 2 -2 2
53   lines
54   21 21 21
55   mappingName
56   box
57   exit
58 exit
59 *
60 generate an overlapping grid
61   box
62   north-pole
63   south-pole
64   done
65   change parameters
66   *   interpolation type
67   *   explicit for all grids
68   ghost points
69   all
70   2 2 2 2 2 2
71   exit
72   compute overlap
73 exit
74 save an overlapping grid
75 sib.hdf
76 sib
77 exit

```

The resulting grid is shown in figure 8.

The cell-centered version can be made with Over-

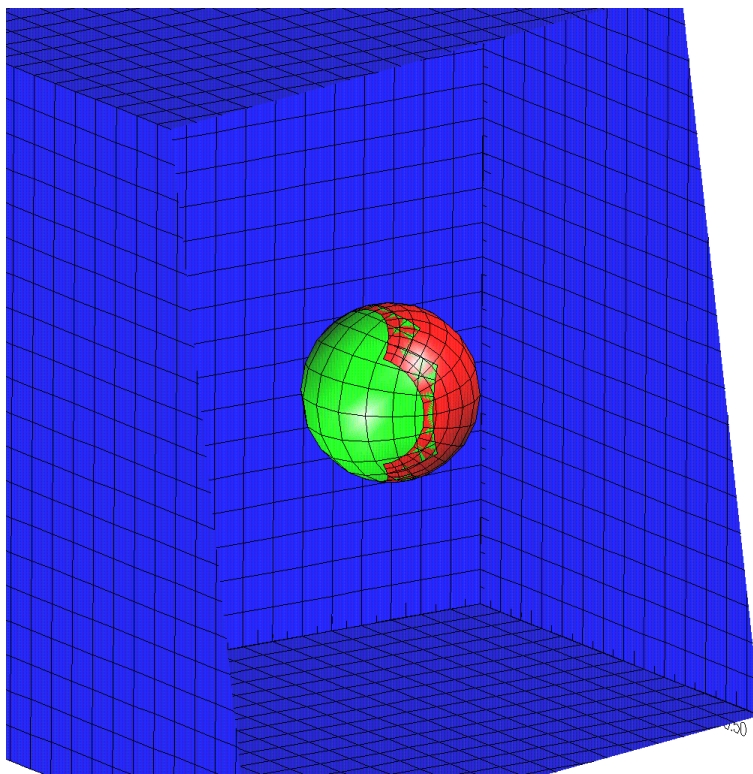


Figure 8: An overlapping grid for a sphere in a box. The sphere is covered with two patches.

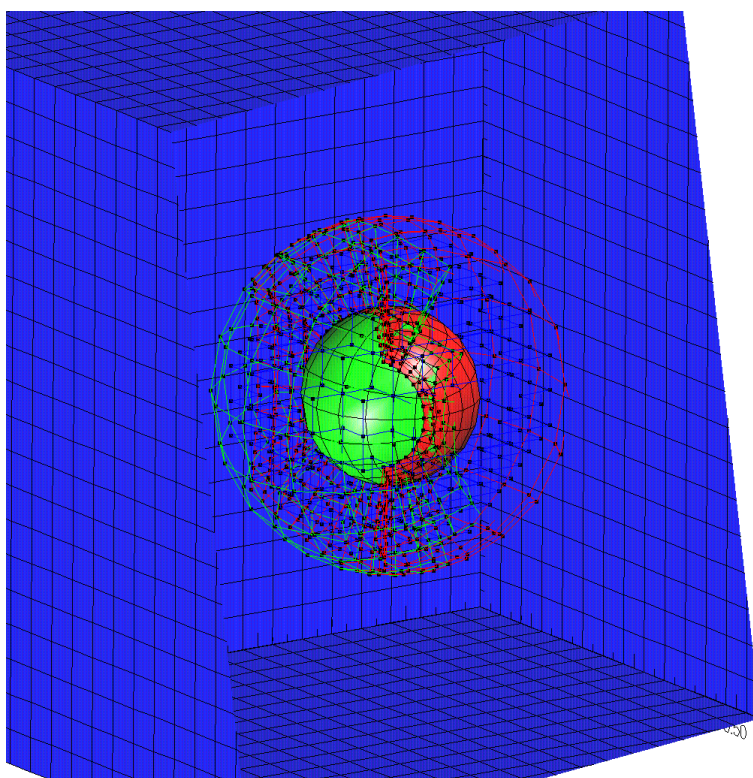


Figure 9: An overlapping grid for a sphere in a box. The interpolation points are also shown.

4.13 Sphere in a tube

Here is a command file to create a sphere in a cylindrical tube. The sphere is covered with two orthographic patches, one for the north-pole and one for the south-pole. The sphere is contained in a tube that is represented as a cylindrical annulus together with a rectangular box that forms the core of the cylinder. (file Overture/sampleGrids/sphereInATube.cmd)

```

1  *
2  * command file to create a sphere in cylindrical tube
3  *
4  *
5  create mappings
6  * first make a sphere
7  Sphere
8  exit
9  *
10 * now make a mapping for the north pole
11 *
12 reparameterize
13   orthographic
14   specify sa,sb
15     2.5 2.5
16   exit
17   lines
18     15 15 5
19   boundary conditions
20     0 0 0 0 1 0
21   share
22     0 0 0 0 1 0
23   mappingName
24     north-pole
25 exit
26 *
27 * now make a mapping for the south pole
28 *
29 reparameterize
30   orthographic
31   choose north or south pole
32     -1
33   specify sa,sb
34     2.5 2.5
35   exit
36   lines
37     15 15 5
38   boundary conditions
39     0 0 0 0 1 0
40   share
41     0 0 0 0 1 0
42   mappingName
43     south-pole
44 exit
45 *
46 * Here is the cylinder
47 *
48 * main cylinder
49 Cylinder
50   mappingName
51     cylinder
52   * orient the cylinder so y-axis is axial direction
53   orientation
54     2 0 1
55   bounds on the radial variable
56     .3 .8
57   bounds on the axial variable
58     -1. 1.
59   lines
60     55 21 9
61   boundary conditions
62     -1 -1 2 3 0 4
63   share
64     0 0 2 3 0 0
65 exit
66 * core of the main cylinder
67 Box
68   mappingName
69     cylinderCore
70   specify corners
71     -.5 -1. -.5 .5 1. .5
72   lines
73     19 21 19
74   boundary conditions
75     0 0 2 3 0 0
76   share
77     0 0 2 3 0 0
78 exit
79 * pause
80 *
81 exit
82 generate an overlapping grid
83   cylinderCore
84   cylinder
85   north-pole
86   south-pole
87 done
88 change parameters
89   ghost points
90     all
91     2 2 2 2 2 2
92 exit
93 * display intermediate
94 compute overlap
95 * continue
96 * pause
97 exit
98 save an overlapping grid
99 sphereInATube.hdf
100 sit
101 exit

```

The resulting grid is shown in figure 10.

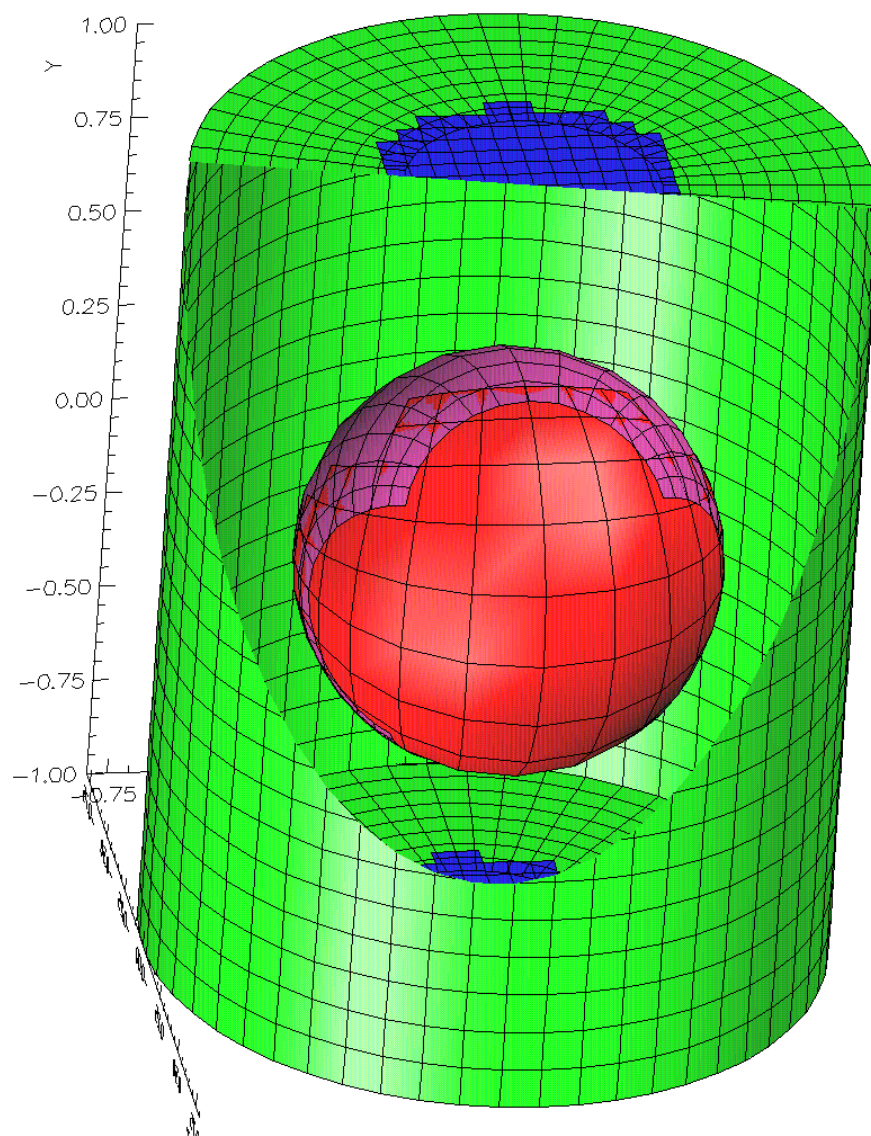


Figure 10: An overlapping grid for a sphere in a cylindrical tube

4.14 Intersecting pipes

Here is a command file to create a grid for two intersecting pipes. Each pipe is made from a cylindrical annulus with a rectangular grid for the core. The pipes intersect using the poor man's intersection method with non-conforming grids. (A more refined intersection would use a fillet). The key point here is that the boundaries must not cut holes and so this feature is turned off. (file Overture/sampleGrids/pipes.cmd)

```

1  *
2  * Make an overlapping grid for two intersecting pipes
3  *   cpu=2s (ov15 sun-ultra optimized)
4  *
5  create mappings
6  * Here is the main pipe
7  Cylinder
8  orientation
9  1 2 0
10 bounds on the radial variable
11 .25 .5
12 bounds on the axial variable
13 -1.5 1.
14 mappingName
15 mainPipe
16 lines
17 25 21 7
18 boundary conditions
19 -1 -1 1 1 0 2
20 share
21 0 0 1 2 0 0
22 exit
23 * Here is the core of the main pipe
24 * note: there is trouble if corner of core just
25 * sticks outside the main pipe -- hole cutter
26 * misses. (happens with core half width= .3)
27 Box
28 specify corners
29 -1.5 -.25 -.25 1. .25 .25
30 lines
31 21 9 9
32 boundary conditions
33 1 1 0 0 0 0
34 mappingName
35 mainCore
36 share
37 1 2 0 0 0 0
38 exit
39 * Here is the branch pipe
40 Cylinder
41 orientation
42 2 0 1
43 bounds on the radial variable
44 .2 .4
45 bounds on the axial variable
46 .25 1.25
47 lines
48 23 11 7 21 11 7
49 boundary conditions
50 -1 -1 0 1 0 2
51 share
52 0 0 0 3 0 0
53 mappingName
54 branchPipe
55 exit
56 * Here is the core of the branch pipe
57 Box
58 specify corners
59 -.25 .25 -.25 .25 1.25 .25
60 lines
61 9 15 9
62 boundary conditions
63 0 0 0 1 0 0
64 share
65 0 0 0 3 0 0
66 mappingName
67 branchCore
68 exit
69 exit
70 generate an overlapping grid
71 branchCore
72 branchPipe
73 mainCore
74 mainPipe
75 done
76 change parameters
77 prevent hole cutting
78 all
79 all
80 done
81 allow hole cutting
82 branchPipe
83 branchCore
84 mainCore
85 mainPipe
86 done
87 ghost points
88 all
89 2 2 2 2 2 2
90 exit
91 * pause
92 compute overlap
93 exit
94 save an overlapping grid
95 pipes.hdf
96 pipes
97 exit

```

The resulting grid is shown in figure 11.

compute overlap

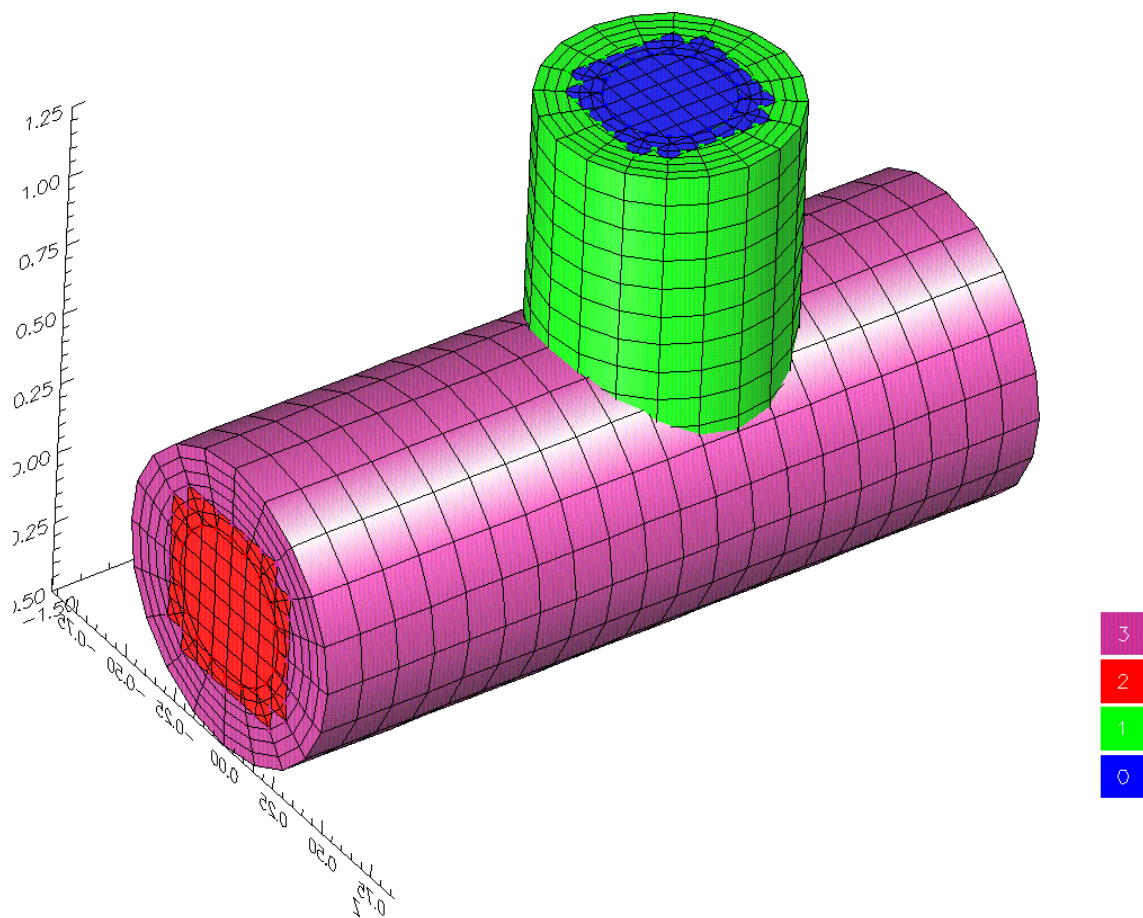


Figure 11: An overlapping grid for two intersecting pipes

4.15 Body Of Revolution

Here is a command file to create a grid for a body of revolution. The body of revolution is created by revolving a two-dimensional grid about a given line. The two dimensional grid in this case is created with the SmoothedPolygon Mapping. The body of revolution has a spherical polar singularity at both ends. We generate a new Mapping to cover each singularity. We reparameterize the ends using an orthographic transformation. (file Overture/sampleGrids/revolve.cmd)

```

1  *
2  * Create a cylindrical body of revolution
3  * from a Smoothed Polygon
4  *   cpu=48s (ov15 sun-ultra optimized)
5  create mappings
6    SmoothedPolygon
7      vertices
8        7
9        -1. 0.
10       -1. .25
11       -.8 .5
12       0. .5
13       .8 .5
14       1. .25
15       1. 0.
16       n-dist
17       fixed normal distance
18       .1
19       n-dist
20       fixed normal distance
21       .4
22       corners
23       specify positions of corners
24       -1. 0.
25       1. 0
26       -1.4 0.
27       1.4 0
28       t-stretch
29       0 5
30       .15 10
31       .15 10
32       0 10
33       .15 10
34       .15 10
35       0 10
36   exit
37 * making a body of revolution
38 * pause
39   body of revolution
40     tangent of line to revolve about
41     1. 0 0
42     mappingName
43     cylinder
44     lines
45     55 25 7
46     boundary conditions
47     0 0 -1 -1 1 0
48     share
49     0 0 0 0 1 0
50   exit
51 * patch on the front singularity
52   reparameterize
53     mappingName
54     front
55     lines
56     15 15 5
57     orthographic
58     specify sa,sb
59     .5 .5
60   exit
61   boundary conditions
62   0 0 0 0 1 0
63   share
64   0 0 0 0 1 0
65   exit
66 * patch on back singularity
67   reparameterize
68     mappingName
69     back
70     lines
71     15 15 7
72     orthographic
73     choose north or south pole
74     -1
75     specify sa,sb
76     .5 .5
77   exit
78   boundary conditions
79   0 0 0 0 1 0
80   share
81   0 0 0 0 1 0
82   exit
83 *
84 * Here is the box
85 *
86   Box
87     specify corners
88     -2 -1 -1 2 1 1
89     lines
90     61 31 31
91     mappingName
92     box
93   exit
94 * pause
95   exit
96   generate an overlapping grid
97   box
98   cylinder
99   front
100  back
101  done
102  compute overlap
103  exit
104  *
105  save an overlapping grid
106  revolve.hdf
107  revolve
108  exit

```

The resulting grid is shown in figure 12.

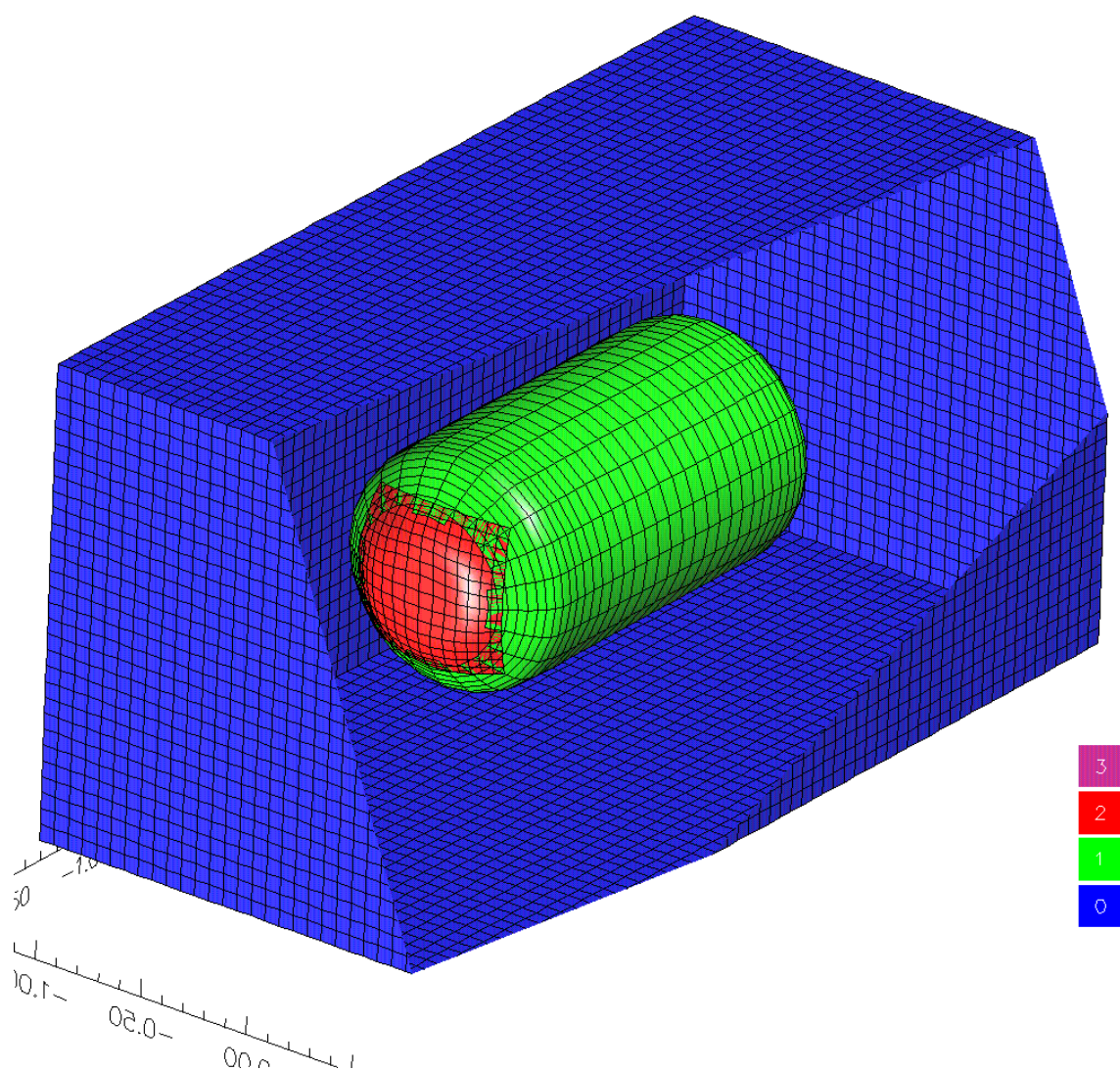


Figure 12: An overlapping grid for a body of revolution. The body is generated by revolving a two-dimensional smoothed-polygon mapping. Orthographic patches are used to cover the singularities at the ends of the body.

4.16 3D valve

Here is a command file to create a grid for a three dimensional valve. The cross-section of this geometry is similar to the two-dimensional valve shown earlier. (file Overture/sampleGrids/valve3d.cmd)

```

1  *                               67      .15
2  * Make a 3d valve              68      lines
3  *                               69      65 17
4  *   cpu=78s (ov15 sun-ultra optimized) 70      sharpness
5  create mappings                71      30
6  * main cylinder                72      30
7  Cylinder                       73      30
8  mappingName                    74      30
9  outerCylinder                  75      boundary conditions
10 * orient the cylinder so y-axis is axial direction 76      0 0 1 0
11 orientation                     77      exit
12 2 0 1                          78 * Make the valve as a body of revolution
13 bounds on the radial variable  79      body of revolution
14 .4 1.                          80      mappingName
15 bounds on the axial variable   81      valve
16 -.1 .5                        82      choose a point on the line to revolve about
17 lines                          83      0. 1. 0.
18 55 11 9                       84      lines
19 boundary conditions            85      41 11 35
20 -1 -1 0 3 0 2                 86      boundary conditions
21 share                         87      0 0 2 0 -1 -1
22 0 0 0 1 0 2                   88      share
23 exit                          89      0 0 3 0 0 0
24 * core of the main cylinder    90      exit
25 Box                            91 * 2D cross section for the stopper
26 mappingName                   92      SmoothedPolygon
27 cylinderCore                  93      mappingName
28 set corners                    94      stopperCrossSection
29 -.5 .5 0. .5 -.5 .5           95      vertices
30 lines                          96      4
31 19 17 19                      97      .65 -.5
32 boundary conditions            98      .65 -.3
33 0 0 1 2 0 0                   99      .85 -.1
34 share                         100     1. -.1
35 0 0 3 1 0 0                   101     n-dist
36 exit                          102     fixed normal distance
37 * valve stem                  103     .15
38 Cylinder                      104     exit
39 mappingName                   105 * stopper
40 valveStem                     106     body of revolution
41 * orient the cylinder so y-axis is axial direction 107     mappingName
42 orientation                     108     stopper
43 2 0 1                          109     choose a point on the line to revolve about
44 bounds on the radial variable  110     0. 1. 0.
45 .2 .6                          111     boundary conditions
46 bounds on the axial variable   112     1 1 2 0 -1 -1
47 -.5 -.2                       113     share
48 lines                          114     4 2 0 0 0 0
49 41 9 9                        115     lines
50 boundary conditions            116     35 11 41
51 -1 -1 3 2 2 0                 117     exit
52 share                         118     view mappings
53 0 0 4 3 0 0                   119     outerCylinder
54 exit                          120     cylinderCore
55 * Make a 2d cross-section of the valve 121     valveStem
56 SmoothedPolygon                122     valve
57 mappingName                    123     stopper
58 valveCrossSection              124     exit
59 vertices                       125     exit
60 4                              126 *
61 .4 0.                          127     generate an overlapping grid
62 .85 0.                         128     cylinderCore
63 .65 -.2                       129     outerCylinder
64 .4 -.2                        130     stopper
65 n-dist                        131     valve
66 fixed normal distance          132     valveStem

```

```

133 done
134 change parameters
135 ghost points
136 all
137 2 2 2 2 2 2
138 exit
139 * pause
140 compute overlap

141 exit
142 save an overlapping grid
143 valve3d.hdf
144 valve3d
145 exit
146
147

```

The resulting grid is shown in figure 13.

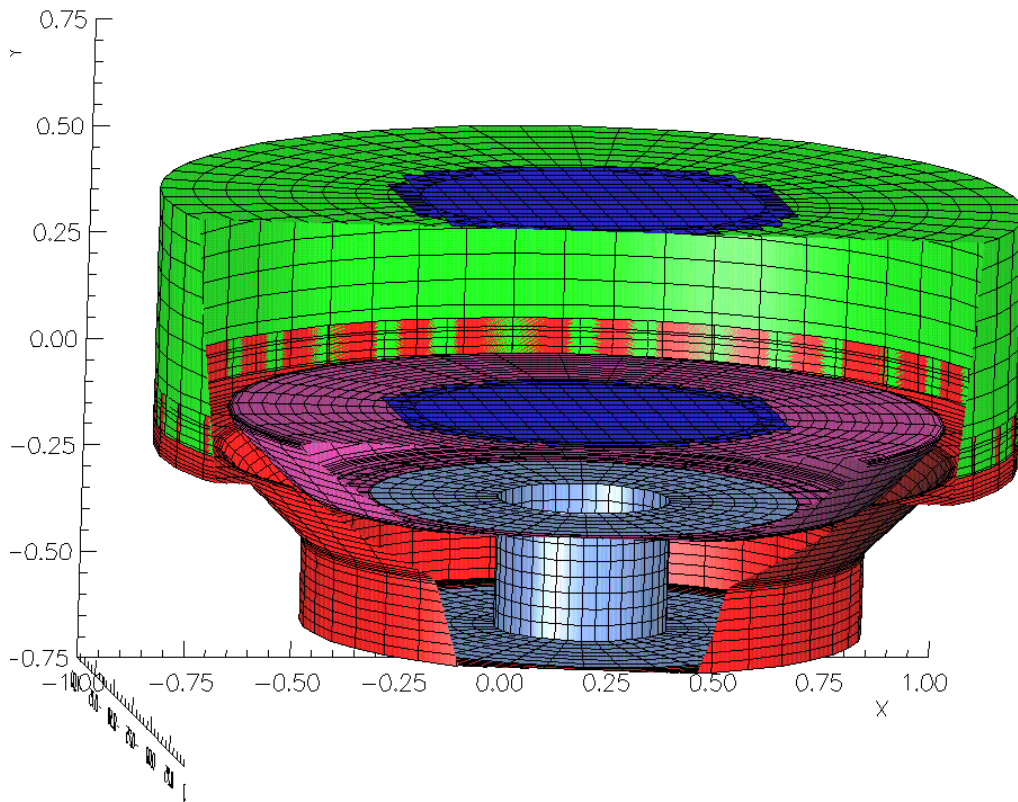


Figure 13: An overlapping grid for a three-dimensional valve.

4.17 Adding new grids to an existing overlapping grid.

New with version 18 This example shows how to start from an existing overlapping grid and add new grids. In this example we begin by building Mappings for two new grids. From the “generate an overlapping grid” menu we read in an existing overlapping grid and then specify the additional mappings. Ogen uses an optimized algorithm to compute the new overlapping grid. If for some reason this algorithm fails you can always choose “reset grid” followed by “compute overlap” to rebuild the grid from scratch.

```

1  *
2  * add mappings to an existing overlapping grid
3  *
4  create mappings
5  *
6  annulus
7  centre
8  1. 1.
9  boundary conditions
10 -1 -1 1 0
11 mappingName
12 annulus2
13 exit
14 *
15 rectangle

16 boundary conditions
17 0 0 0 0
18 set corners
19 -1.5 -.5 -1.5 -.5
20 mappingName
21 refine
22 exit
23 *
24 exit this menu
25 generate an overlapping grid
26 read in an old grid
27 cic
28 annulus2
29 refine
30

```

The resulting grid is shown in figure 14.

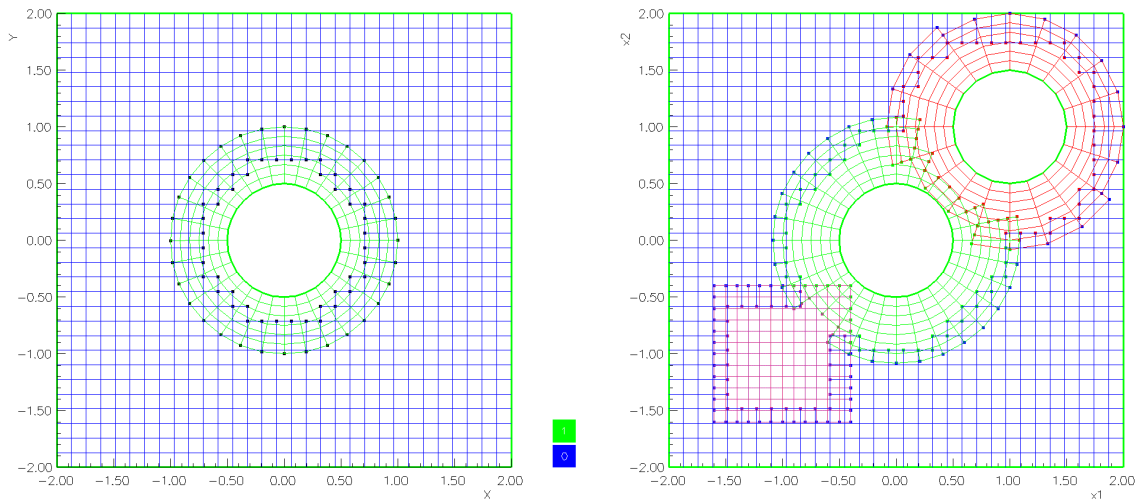


Figure 14: Ogen can be used to incrementally add new grids to an existing overlapping grid. Left: The initial overlapping grid. Right: overlapping grid after adding two new component grids

4.18 Incrementally adding grids to an overlapping grid.

New with version 18 This example shows how to incrementally add new grids to an overlapping grid. As new grids are added the overlapping grid can be re-computed to make sure that a valid grid exists. This can be a useful approach for building a large complicated grid since any problems will be isolated to the component grid that may have caused an invalid grid to result.

```

1  create mappings
2    rectangle
3    lines
4      41 41
5    mappingName
6    backGround
7    exit
8  *
9    annulus
10   inner and outer radii
11     .1 .2
12   lines
13     21 5
14   centre for annulus
15     .25 .25
16   boundary conditions
17     -1 -1 1 0
18   mappingName
19     annulus1
20   exit
21  *
22   annulus
23   inner and outer radii
24     .1 .2
25   lines
26     21 5
27   centre for annulus
28     .6 .35
29   boundary conditions
30     -1 -1 1 0
31   mappingName
32     annulus2
33   exit
34  *
35   annulus
36   inner and outer radii
37     .1 .2
38   lines
39     21 5
40   centre for annulus
41     .35 .65
42   boundary conditions
43     -1 -1 1 0
44   mappingName
45     annulus3
46   exit
47  *
48   annulus
49   inner and outer radii
50     .1 .2
51   lines
52     21 5
53   centre for annulus
54     .7 .65
55   boundary conditions
56     -1 -1 1 0
57   mappingName
58     annulus4
59   exit
60   exit this menu
61   generate an overlapping grid
62   backGround
63   done choosing mappings
64   compute overlap
65   pause
66   add grids
67   annulus1
68   done choosing mappings
69   compute overlap
70   pause
71   add grids
72   annulus2
73   done choosing mappings
74   compute overlap
75   pause
76   add grids
77   annulus3
78   done choosing mappings
79   compute overlap
80   pause
81   add grids
82   annulus4
83   done choosing mappings
84   compute overlap
85

```

The resulting grids at various stages are shown in figure 15.

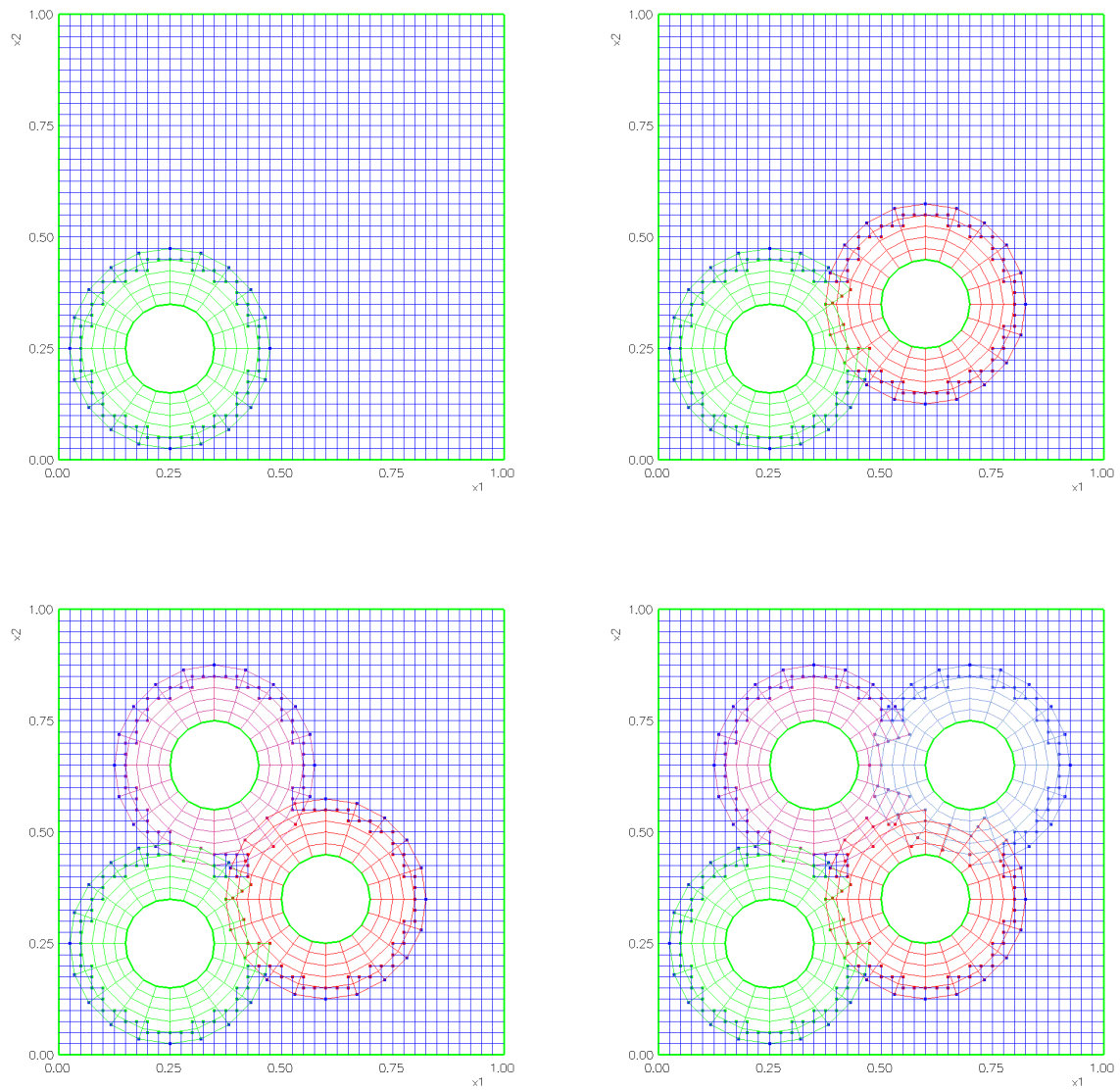


Figure 15: Ogen can be used to incrementally add new grids.

4.19 Other sample command files and grids

The `Overture/sampleGrids` directory contains a number of other command files for creating grids. We list these here with a brief explanation.

cilc.cmd : Two dimensional cylinder in a long box. Used for computing the flow around a cylinder.

ellipsoid.cmd : Create a grid for a three-dimensional ellipsoid in a box. See also `ellipsoidCC.cmd` for the cell-centered version.

singularSphere.cmd : Build a grid for a sphere in a box where the singularities on the sphere are not removed. A PDE solver must know how to deal with this special type of grid.

tse.cmd : Build a grid for a model two-stroke engine.

mastSail2d.cmd : Make a grid for a sail attached to a mast.

building3.cmd : Three dimensional grids for some buildings.

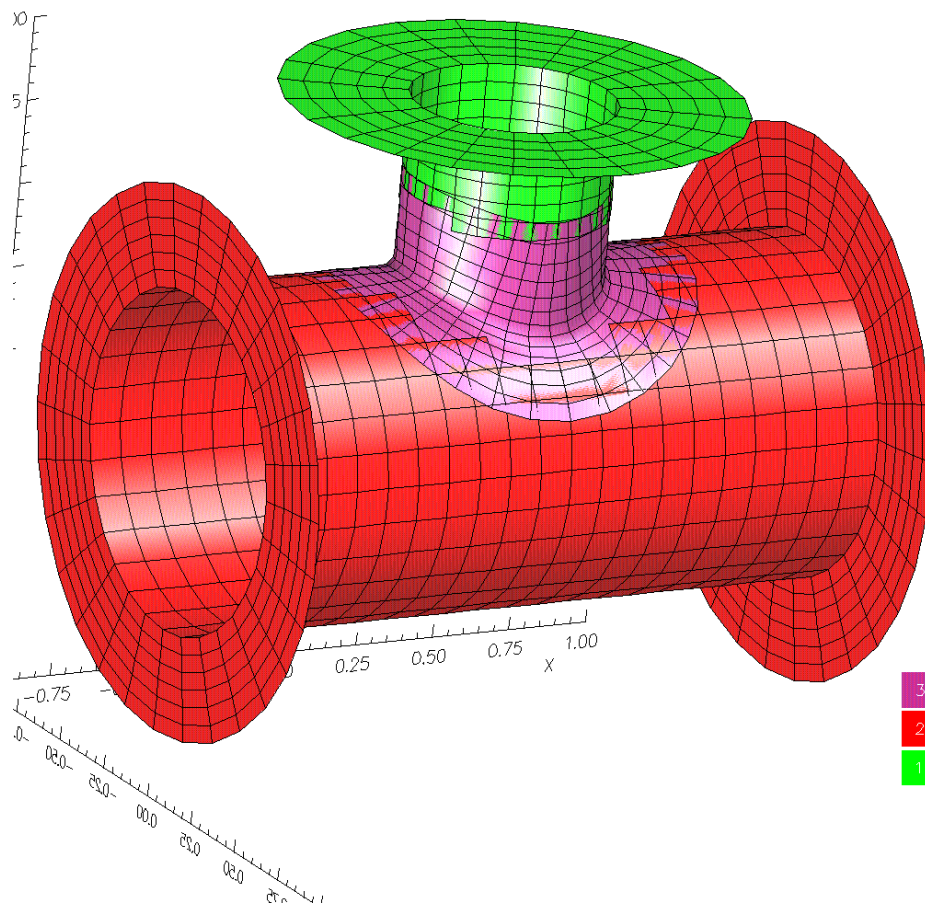


Figure 16: A fillet grid is used to join two cylinders, `filletTwoCyl1.cmd`.

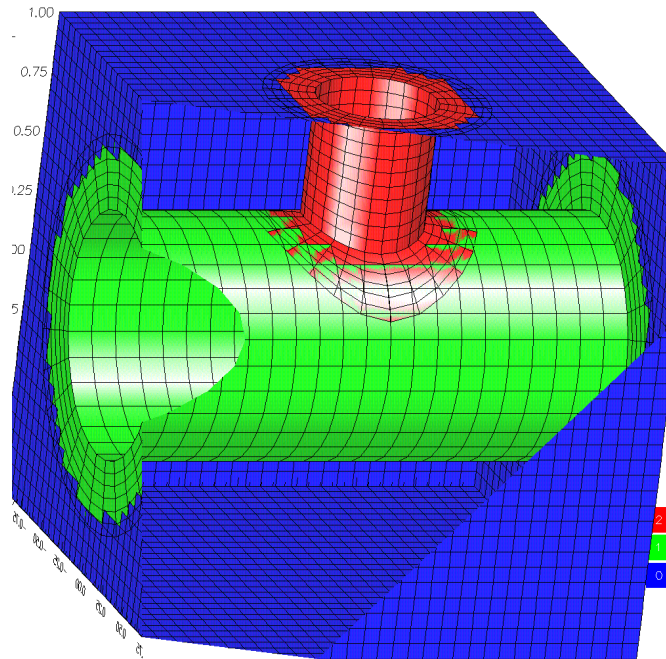


Figure 17: A JoinMapping is used to join two cylinders, `joinTwoCyl.cmd`. To create the deformed cylinder the JoinMapping first computes the curves of intersection between two intersecting cylinders. Four TFIMappings are then generated to represent each face of the deformed cylinder and finally another TFIMapping is used to blend these four surface TFIMappings.

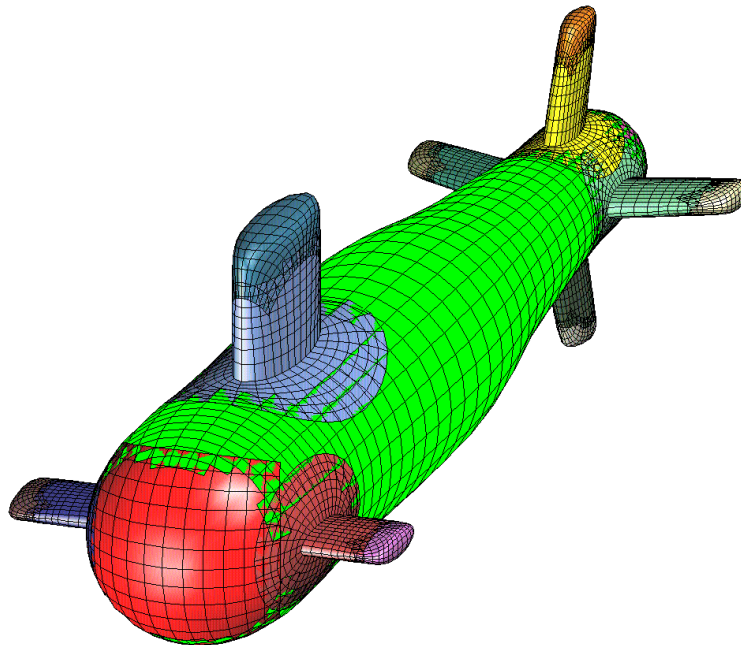


Figure 18: An overlapping grid for a submarine created with `sub.cmd`. The submarine hull is defined as a body of revolution from a spline curve. The sail and fins are created initially with the CrossSectionMapping. The JoinMapping is used to join these appendages to the submarine body.

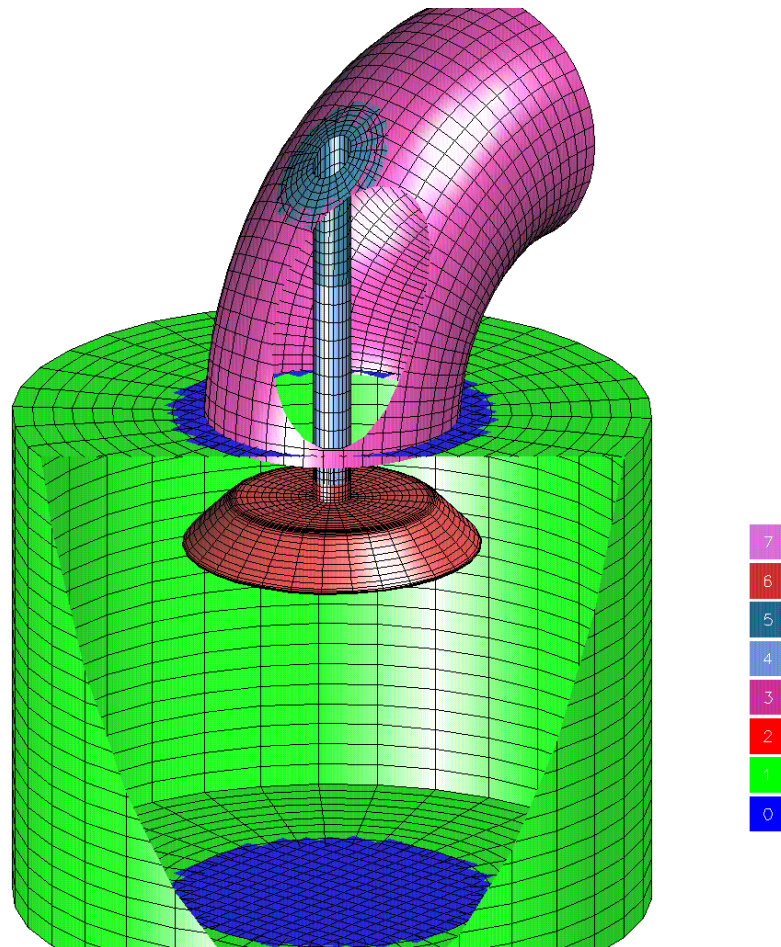


Figure 19: An overlapping grid for valve, port and cylinder created with `valvePort . cmd`. The `JoinMapping` is used to create the grid that joins the valve-stem to the port surface.

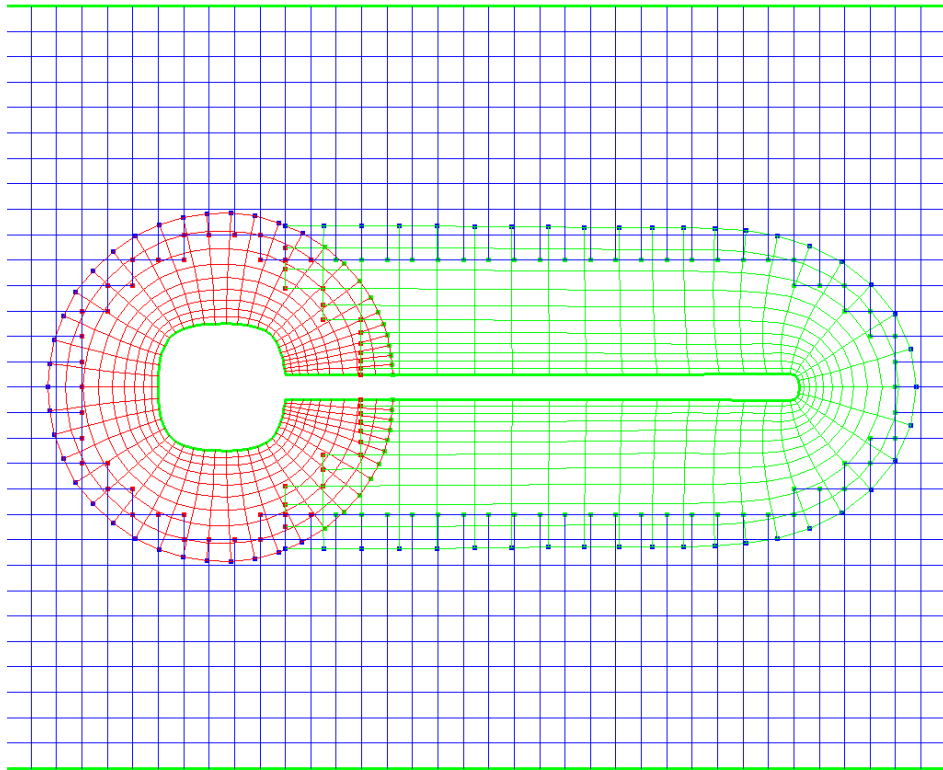


Figure 20: A mast is attached to a sail. The inner boundary curves are defined from splines under tension while the component grids are generated with hyperbolic grid generation `mastSail2d.cmd`

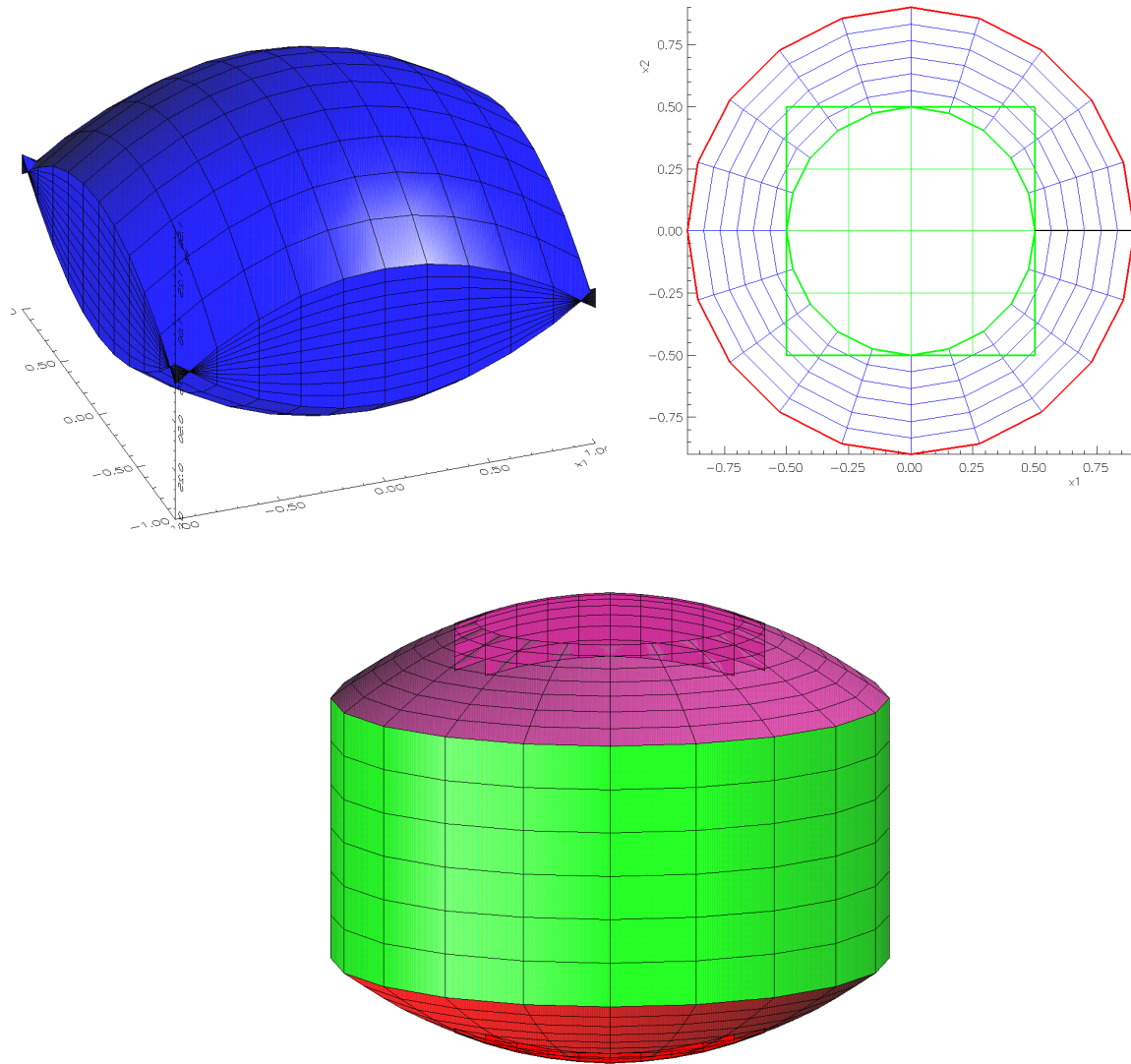


Figure 21: The DepthMapping (see bottom figure) is used to give a vertical dimension to mappings defined in the plane, `depth.cmd`. In this case a separate TFI mapping, top left, defines the vertical height function. Both an annulus and a square (top right) are given a depth.

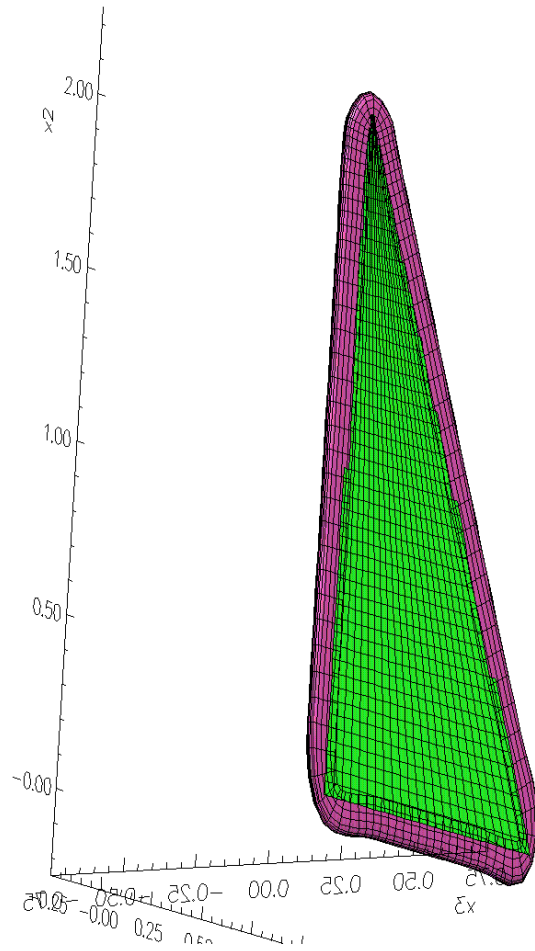


Figure 23: Grid for a 3d triangular sail. The SweepMapping is used to generate a grid around the edge of the sail, `tri-Sail.cmd`

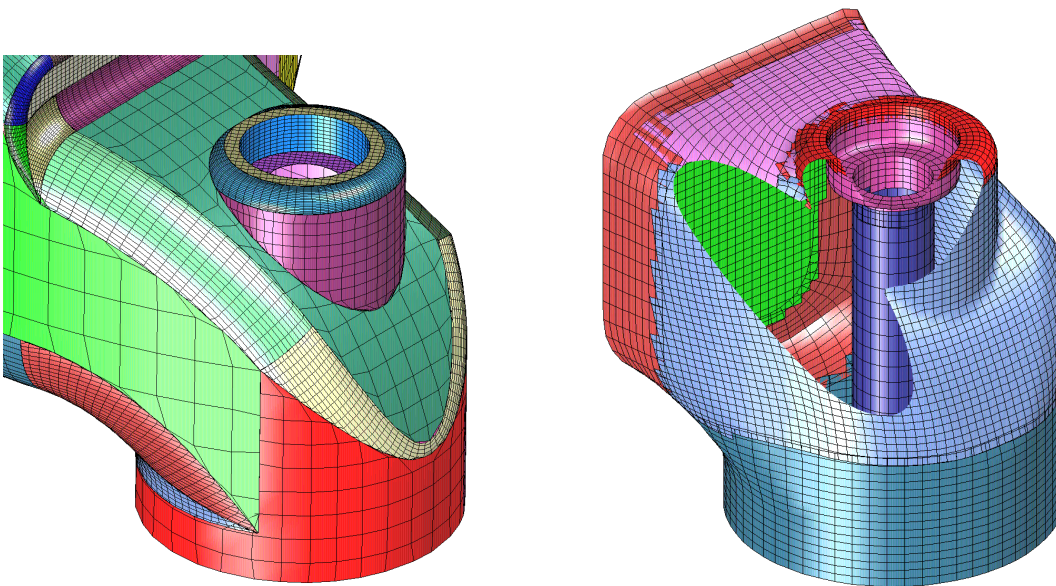


Figure 24: CAD surface (left) and a volume mesh (right) generated with Overture Mappings and Ogen.

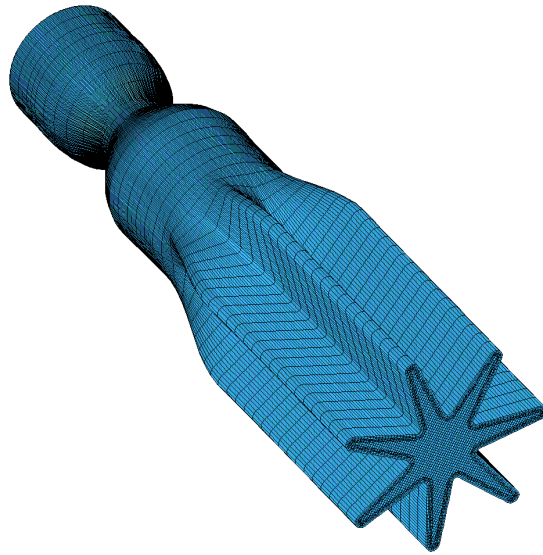


Figure 25: Grid for the core of a rocket, showing the fuel-grain star-pattern. Rocket shape was created with the cross-section mapping and curves defined by the `RocketMapping` class. Thanks to Nathan Crane for building this grid.

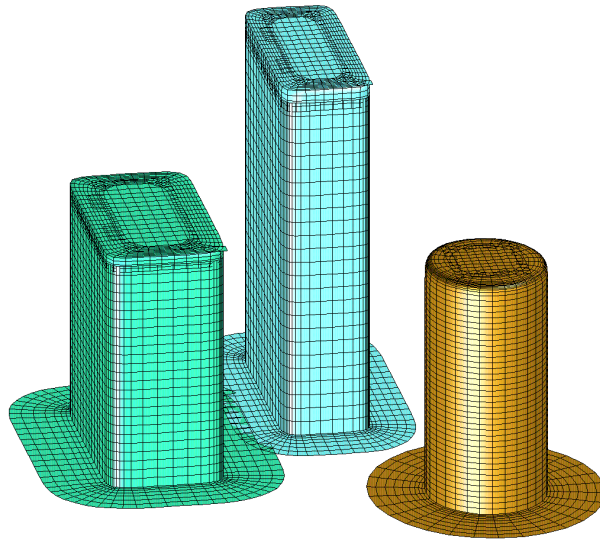


Figure 26: Grid for some buildings built with `building3.cmd`

5 Mixed physical-interpolation boundaries, making a c-grid, h-grid or block-block grid

To make a 'c-grid' as in figure (27) or an 'h-grid' as in figure (28) or the two block grid of figure (29), one should use the 'mixed boundary' option from the change parameters menu. A mixed boundary is a physical boundary where parts of the boundary can interpolate from another (or the same) grid. Actually it is either the boundary points or the ghost points on parts of the boundary that interpolate from another grid. When solving a PDE boundary value problem, the boundary points adjacent to ghost points that interpolate will be 'interior points' where the PDE should be applied, rather than the boundary condition. A mixed boundary on a MappedGrid `g` will have `g.boundaryCondition(side,axis) > 0` and `g.boundaryFlag(side,axis)==MappedGrid::mixedPhysicalInterpolationBoundary`.

There are two ways to determine which points on a mixed boundary should be interpolated

1. **Automatic:** With this option the program will attempt to find all the valid interpolation points. For the automatic determination of the mixed boundary interpolation points you can specify the tolerance for matching in two possible ways:

r matching tolerance : boundaries match if points are this close in unit square space.

x matching tolerance : boundaries match if points are this close in x space

The boundaries will be deemed to match if either one of the above two matching conditions holds.

2. **Manual:** with this option one must explicitly specify a set of points on the boundary that should be interpolated from another grid. One also indicates whether to interpolate boundary points or ghost points. If there are multiple disjoint regions to interpolate, each one should be specified separately. Even when points are specified in this **manual** case the program will still check to see if the points can be interpolated in a valid manner (and only interpolate those valid ones) using the **r matching tolerance** described above.

5.1 Automatic mixed-boundary interpolation

It is recommended when making a c-grid or an h-grid to have the matching parts of the boundaries actually overlap by an amount greater than or equal to zero (as shown in the examples).

The c-grid was generated with the command file `Overture/sampleGrids/cgrid.cmd`. A c-grid has a special topology where parts of the boundary of the c-grid actually become interior points with a periodic like boundary condition. This is implemented in Ogen by the 'mixed boundary' option. Along the c-grid 'branch cut', ghost point values interpolate from the opposite side of the c-grid.

Note that the c-grid boundary was made with a spline that wiggles a little bit along the branch cut. To ensure that the branch cut would be properly found, the lower part of the cut was raised by a small amount so that it would overlap the upper part of the grid (and vice versa to be symmetric). One can also specify a matching tolerance to take care of this problem, but it is more robust to use this trick of overlapping the branch cut a little bit. A matching tolerance was actually specified here, to be safe, but a message printed from ogen indicated that it was not needed. The h-grid was generated with the command file `Overture/sampleGrids/hgrid.cmd`. An h-grid has a special topology where parts of the boundary of the h-grid actually become interior points that match up to a second grid. This is implemented in Ogen by the 'mixed boundary' option. Along the h-grid 'branch cut', ghost point values interpolate from the other grid.

Note that the h-grid boundaries were made with splines that wiggle a little bit along the branch cuts (matching portions). To ensure that the branch cuts would be properly found, the lower part of the cut was raised by a small amount so that it would overlap the upper part of the grid (and vice versa to be symmetric). One can also specify a matching tolerance to take care of this problem, but it is more robust to use this trick of overlapping the branch cut a little bit. A matching tolerance was actually specified here, to be safe, but a message printed from ogen indicated that it was not needed.

The grid in figure (29) was generated with the command file `Overture/sampleGrids/twoBlock.cmd`.

5.2 Manual specification of mixed-boundary interpolation points

The command file `cgrid.manual.cmd` found in the `Overture/sampleGrids` directory shows how to manually create a c-grid by specifying which points should be interpolated. Note that we specify how points on the bottom of the c-grid branch cut interpolate from the top (along the ghost points) and how points on the top boundary interpolate from the bottom.

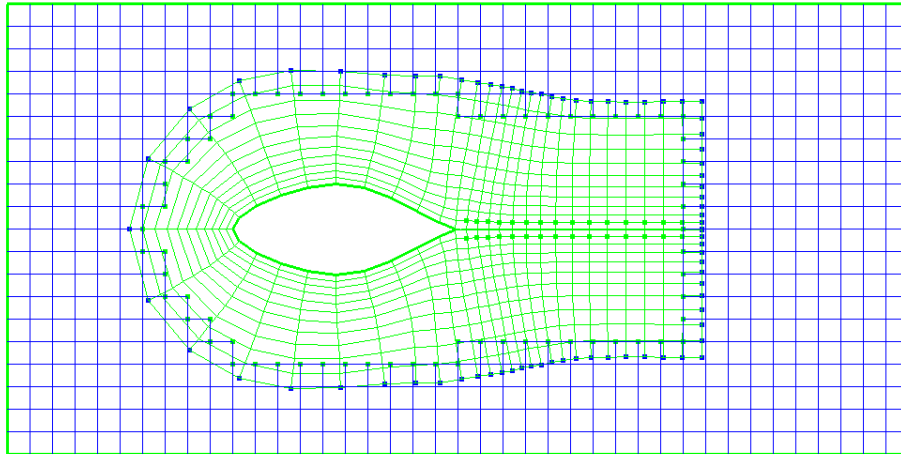


Figure 27: An overlapping grid using a c-grid makes use of the 'mixed boundary' option. A mixed-boundary is a boundary that is sometimes a physical boundary of the domain and sometimes an interpolation boundary.

5.3 Spitting a grid for interpolation of a grid to itself

When mixed boundary interpolation points are to be interpolated from the same grid (as in the case of a c-grid) ogen will actually temporarily split the grid into two pieces and determine how points on one piece interpolate from the other. This is necessary to prevent points from interpolating from themselves. By default, for a mixed boundary on (side,axis) the grid is split at the halfway point along $(axis+1) \bmod numberOfDimensions$. If this is not correct you should explicitly specify where to split the grid using the `specify split for self interpolation` option. In this case you specify the axis that should be split and the index position of the split.

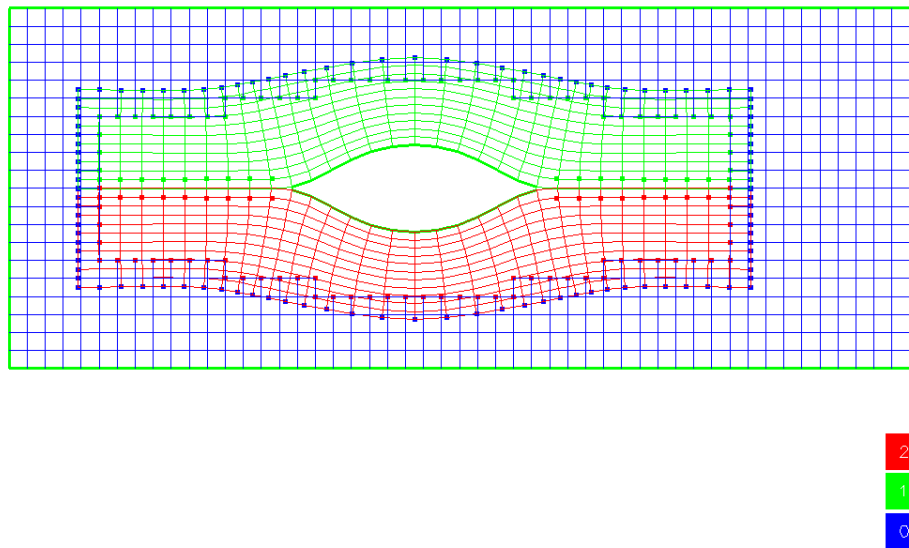


Figure 28: An overlapping grid using an h-grid makes use of the 'mixed boundary' option.

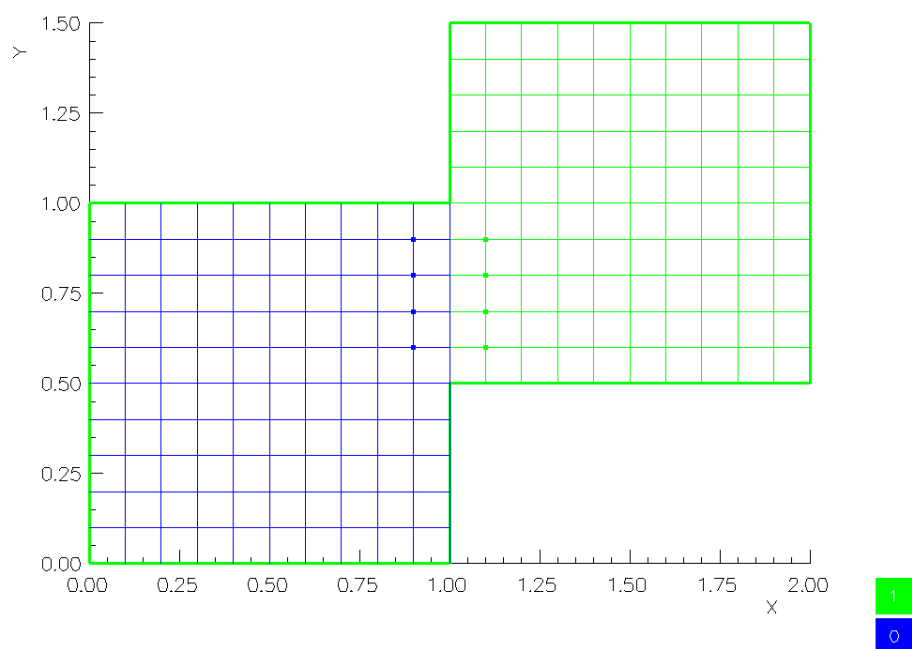


Figure 29: An overlapping grid for two blocks makes use of the 'mixed boundary' option.

6 Manual Hole Cutting and Phantom Hole Cutting

Ogen's hole cutting algorithm can make mistakes in some difficult cases such as when there are thin bodies. There is a *manual hole cutting* option that can be used in these difficult cases. Recall that when ogen cuts a hole with the boundary of grid g_0 it marks points on grid g_1 that lie near the boundary of g_0 . Points on g_1 are marked as interpolation or as hole points depending on whether they are inside or outside grid g_0 . The hole cutting algorithm can make a mistake if there is a grid g_2 that is very close to the boundary of g_0 but which should not be cut. Normally one can fix this problem by choosing the option *prevent hole cutting* of g_0 in g_2 ; however there are some cases when one must allow g_0 to cut some holes in a different portion of g_2 .

There are two steps to perform manual hole cutting:

1. Specify *phantom hole cutting* for grid g_0 onto grid g_1 . In this case only interpolation points on g_1 will be marked near the boundary of g_0 ; no hole points will be marked. These interpolation points should completely surround the hole region.
2. Manually cut a small hole in grid g_1 using the *manual hole cutting* option. The hole points that are specified must lie within the region of g_1 that should be removed. These hole points will act as a seed and will be swept out to fill the entire hole region. If the manually placed hole points are put in the wrong location then the hole points may expand throughout much of the grid, resulting in an invalid overlapping grid.

The command files `cicManualHoleCut.cmd` and `sibManualHoleCut.cmd` in the `Overture/sampleGrids` directory show examples of manually cutting holes.

7 Trouble Shooting

In this section we give some hints on what to do when you are unable to build a grid.

When there is not enough overlap between the grids or you have made a mistake in specifying the boundary conditions or share flag values etc. the grid generator will fail to build a grid. When the algorithm fails the grid will be plotted and the offending points will be plotted with black marks. In addition information is printed to the screen and to a log file, `ogen.log` that may be helpful in tracking down what went wrong.

7.1 Failure of explicit interpolation

As an example, in figures (30) and (31) we show the result of trying to use `explicit interpolation` with the two-dimensional valve grid. The algorithm fails to interpolate some points. These points are plotted with black marks.

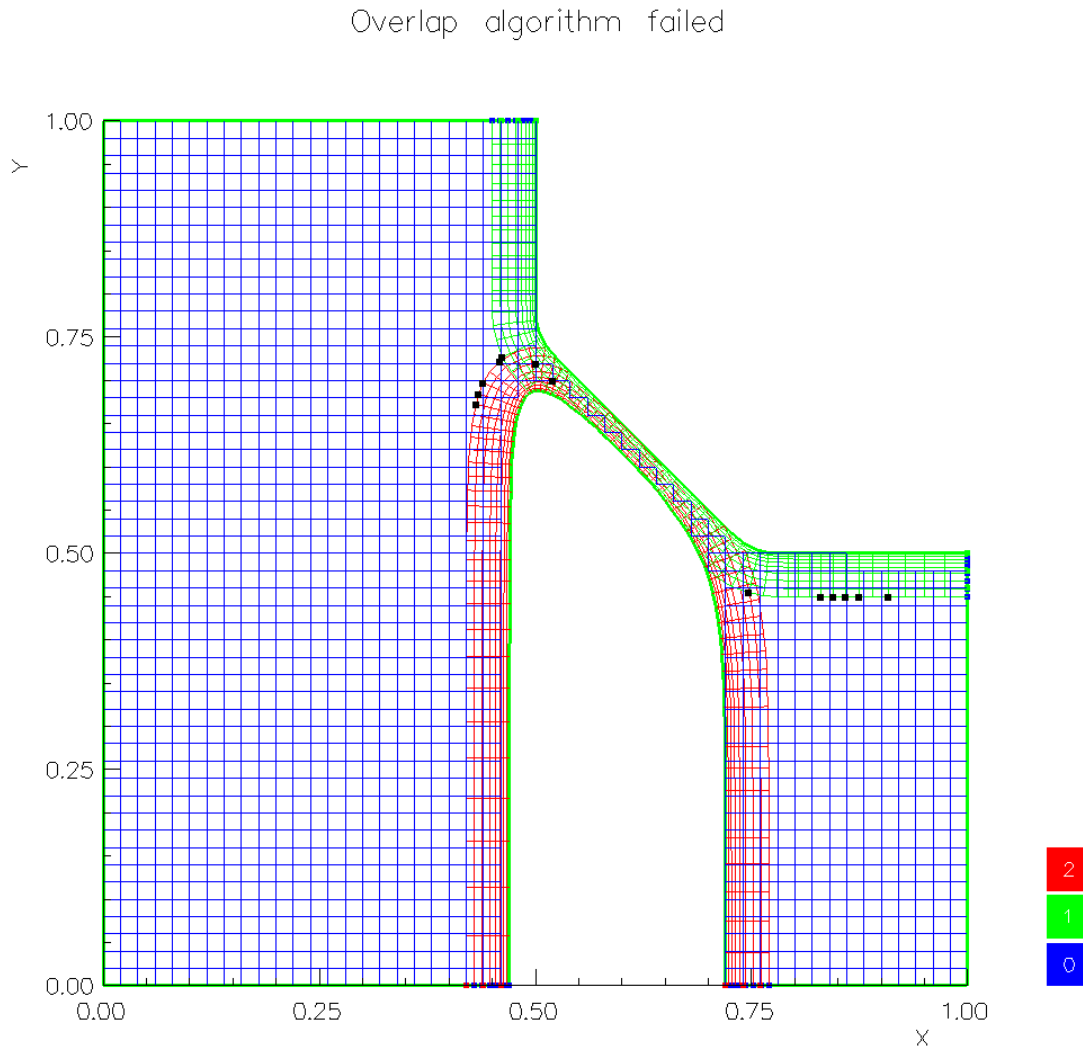


Figure 30: An example showing the failure of the overlapping grid algorithm when there is insufficient overlap. We have tried to use explicit interpolation for the two-dimensional valve. The algorithm fails and plots the offending points with black marks.

When the algorithm fails there is information written to the file `ogen.log`. In this case the file contains information on each point that failed, as for example:

```
ERROR: unable to interpolate a point on grid=backGround, (i1,i2,i3)=(26,35,0), x=( 5.200e-01, 7.000e-01, 0.000e+00)
Try to interpolate from grid=stopper, r=(6.66e-01,5.96e-01,0.00e+00)
```

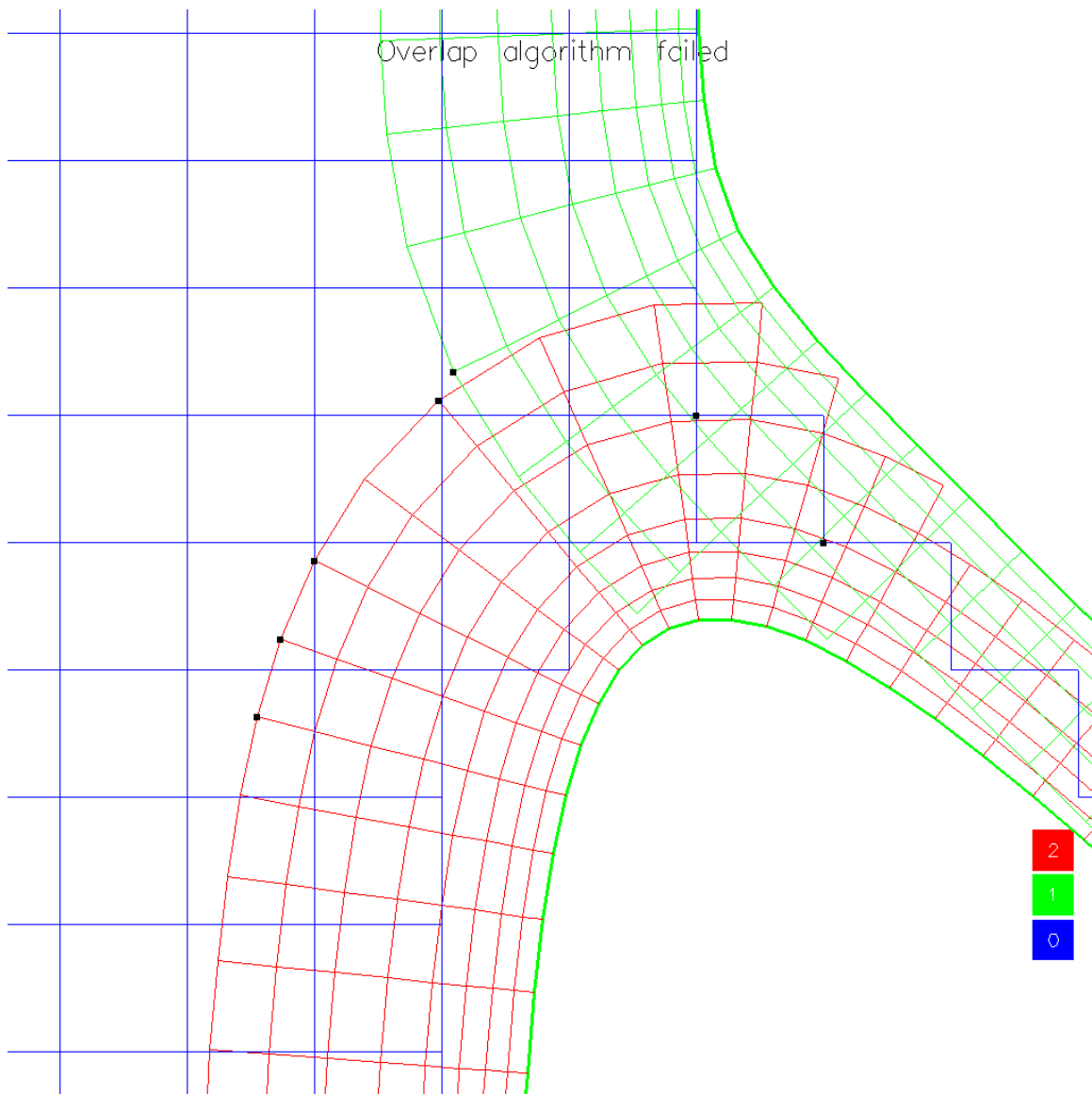


Figure 31: A magnification of the failed grid shows that the points marked in black cannot be interpolated in an explicit manner using a 3×3 interpolation stencil.

```
mask = [1][1][1][-1][1][1][-1][-1][-1] : 0=hole, -1=interp., 1=discret.
...point is inside but explicit interpolation failed because stencil has an interpolation point in it.
Try to interpolate from grid=valve, r=(4.27e-01,4.84e-01,0.00e+00)
mask = [1][1][1][1][1][1][1][1][-1] : 0=hole, -1=interp., 1=discret.
...point is inside but explicit interpolation failed because stencil has an interpolation point in it.
```

This information indicates that a point could not be interpolated from either of two possible grids since the 9-point interpolation stencil (indicated by the 9 values of mask) contains some points that are themselves interpolation points (mask=-1). The values of r indicate the unit square coordinates in the grid we are trying to interpolate from.

Possible solutions to this problem are to use implicit interpolation or to increase the number of grid points on the grids or to decrease the interpolation width.

7.2 Tips

Here are some tips for fixing a grid that fails:

check the log file: Check the ogen log file, **ogen.log** for informational messages that may help you understand what went wrong.

display intermediate results: Turn on the option ‘**display intermediate results**’ in the **ogen** menu before choosing the option ‘**compute overlap**’. This will plot the grid at intermediate stages in the overlapping grid algorithm.

check the mappings: It is possible that the one of the Mapping’s you have created has an error in it. There is a function available to check the properties of a Mapping. The Mapping can be checked either when you create the Mappings (use the ‘`check mapping`’ option) or from the grid generation menu. The `checkMapping` function will report any errors it finds. For example it will check the derivatives of the mapping by using finite differences. There is probably no reason to be concerned if the relative errors in the derivatives are small, less than 10^{-2} say.

Use implicit interpolation: As mentioned in section (3.5) implicit (default) interpolation requires less overlap than explicit interpolation. If you are using explicit interpolation you could turn on implicit interpolation.

check boundary conditions: Use the `view mappings` option under `create mappings` to view all the mappings. Check that all physical boundaries are shown as a positive value, that interpolation boundaries have a zero value and that periodic boundaries are black.

check for sufficient overlap: Use the `view mappings` option under `create mappings` to view the mappings and check that the mappings appear to overlap sufficiently. If there is not sufficient overlap then **increase the number of grid points**.

check the share flag: use the `view mappings` option under `create mappings` and plot the boundaries by their share flag value. Make sure that different grids that share the same boundary have the same share flag value (see section (3.2) for a description of share flags).

shared side tolerance: even if your share flags are correct, the grid generator has a relative tolerance that it uses to allow for discrepancies between the boundary representations of two grids. This tolerance measures the distance in grid cells that the boundaries can differ by and still be assumed to be the same boundary. If your boundaries do not match closely then you may need to increase this value with the `shared boundary tolerance` option that is available from the `change parameters` menu.

turn off hole cutting: As described in section (3.3), by default physical boundaries will cut holes in other nearby grids. You may need to disable the hole cutting as shown in the “inlet outlet” example, section (4.7).

8 Adding user defined Mapping's

Advanced users of Overture may want to write their own Mapping class, see the Mapping class documentation for how to do this. If you want to add a new type of Mapping to ogen then you should copy and change the driver program `ogenDriver.C` (found in Overture/in) and add in your new Mapping. Compile and load this program to make your own version of ogen.

The next listing shows `ogenDriver.C`. If the preprocessor macro `ADD_USER_MAPPINGS` is defined (for example, by adding the compile flag `-DADD_USER_MAPPINGS` then a user defined `AirfoilMapping` will be added.

```

1 //=====
2 // Here is the driver program for 'ogen' - the overlapping grid generator
3 //
4 // Usage: type
5 //     ogen
6 // to run with graphics, or type
7 //     ogen noplot
8 // to run without graphics, or
9 //     ogen file.cmd
10 // to run ogen with graphics and read in a command file, or
11 //     ogen noplot file.cmd
12 // to run ogen without graphics and read in a command file.
13 //
14 // By default user commands will be saved in the file "ogen.cmd"
15 //
16 // You can add to the driver any nonstandard Mapping's that you want to use.
17 // See the example below where (if the macro ADD_USERMAPPINGS is defined) an AirfoilMapping
18 // is created and added to a list. The list is then passed to ogen. The Mapping
19 // can be subsequently changed within ogen, if required.
20 //
21 // Thus, for example, your compile line should look something like:
22 //     CC -DADD_USERMAPPINGS .... ogenDriver.C
23 //
24 //=====
25
26 #include "Overture.h"
27 #include "MappingInformation.h"
28 #include "PlotStuff.h"
29
30 // Here are some user defined mappings
31 #ifdef ADD_USER_MAPPINGS
32 #include "AirfoilMapping.h"
33 int addToMappingList(Mapping & map);
34 #endif
35
36 int ogen(MappingInformation & mappingInfo, GenericGraphicsInterface & ps, const aString & commandFileName );
37
38 int
39 main(int argc, char *argv[])
40 {
41     Overture::start(argc,argv);
42     // Index::setBoundsCheck(off);
43
44     aString commandFileName="";
45     if( argc > 1 )
46     { // look at arguments for "noplot" or some other name
47         aString line;
48         for( int i=1; i<argc; i++ )
49         {
50             line=argv[i];
51             if( line=="noplot" || line=="nopause" || line=="abortOnEnd" || line=="nodirect" )
52                 continue; // these commands are processed by getGraphicsInterface below
53             else if( commandFileName=="" )
54                 commandFileName=line;
55         }
56     }
57     else
58         cout << "Usage: 'ogen [noplot][nopause][abortOnEnd][file.cmd]' \n"
59              << "        noplot:  run without graphics \n"
60              << "        nopause: do not pause \n"
61              << "        abortOnEnd: abort if command file ends \n"
62              << "        file.cmd: read this command file \n";
63

```

```

64 // --- create user defined mappings ----
65 MappingInformation mappingInfo;
66 #ifdef ADD_USER_MAPPINGS
67     AirfoilMapping airfoil;
68     mappingInfo.mappingList.addElement(airfoil);
69     // Do this so we can read the airfoil mapping from a data-base file
70     addToMappingList(airfoil);
71 #endif
72
73
74 // Graphics interface:
75 // Note: options "noplot", "nopause" and "abortOnEnd" are handled in the next call:
76 GenericGraphicsInterface & ps = *Overture::getGraphicsInterface("ogen: Overlapping Grid Generator",false,argc,argv);
77
78 // By default start saving the command file called "ogen.cmd"
79 aString logFile="ogen.cmd";
80 ps.saveCommandFile(logFile);
81 cout << "User commands are being saved in the file '" << (const char *)logFile << "'\n";
82
83 // create more mappings and/or make an overlapping grid
84 ogen( mappingInfo,ps,commandFileName);
85
86 Overture::finish();
87 return 0;
88 }
89
90
91
92

```


9 Overlapping Grid Generator: Ogen

The overlapping grid generation algorithm determines how the different component grids communicate with each other. The algorithm must also determine those parts of component grids that are removed from the computation because that part of the grid either lies underneath another grid of higher priority or else that part of the grid lies outside the domain.

9.1 Command descriptions

9.1.1 Interactive updateOverlap

int

updateOverlap(CompositeGrid & cg, MappingInformation & mapInfo)

Description: Here is a description of some of the commands that are available from the updateOverlap function of Ogen. This function is called when you choose “generate overlapping grid” from the ogen program.

compute overlap : this will compute the overlapping grid. As the grid is generated various information messages are printed out. Some of these messages may only make sense to the joker who wrote this code.

change parameters : make changes to parameters. See the next section for details.

display intermediate results : this will toggle a debugging mode. When this mode is on, and you choose compute overlap to generate the grid, then the overlapping grid will be plotted at various stages in its algorithm. The algorithm is described in section (9.2). The program will pause at the end of each stage of the algorithm and allow you to either continue or to change the plot as described next. Experienced users will be able to see when something goes wrong and hopefully detect the cause.

change the plot : this will cause the grid to be re-plotted. You will be in the grid plotter menu and you can make changes to the style of the plot (toggle grids on and off, plot interpolation points etc.). These changes will be retained when you exit back to the grid generator.

9.1.2 Non-interactive updateOverlap

int

updateOverlap(CompositeGrid & cg)

Description: Build a composite grid non-interactively using the component grids found in cg. This function might be called if one or more grids have changed.

Return value: 0=success, otherwise the number of errors encountered.

9.1.3 Moving Grid updateOverlap

int

updateOverlap(CompositeGrid & cg,
 CompositeGrid & cgOld,
 const LogicalArray & hasMoved,
 const MovingGridOption & option =useOptimalAlgorithm)

Description: Determine an overlapping grid when one or more grids has moved. **NOTE:** If the number of grid points changes then you should use the useFullAlgorithm option.

cg (input) : grid to update

cgOld (input) : for grids that have not moved, share data with this CompositeGrid.

hasMoved (input): specify which grids have moved with hasMoved(grid)=TRUE

option (input) : An option from one of:

```
enum MovingGridOption
{
    useOptimalAlgorithm=0,
    minimizeOverlap=1,
    useFullAlgorithm
};
```

The useOptimalAlgorithm may result in the overlap increasing as the grid is moved.

Return value: 0=success, otherwise the number of errors encountered.

hangeParametersInclude.tex

9.2 Algorithm

The algorithm used by Ogen is based upon the original CMPGRD algorithm[1] with some major changes to improve robustness. The basic improvement is that the new algorithm initially removes all grid points that lie inside “holes” in the grids. Once the holes have been cut the program can determine explicitly whether there is enough overlap to generate an overlapping grid and if there is not enough overlap the offending points can be shown.

The algorithm for computing the overlapping grid communication is perhaps most easily understood by reading the following description and also referring to the series of examples that follow.

Here are the basic steps in brief:

interpolate boundaries: First try to interpolate points on physical boundaries from points on physical boundaries of other grids.

Boundary points that interpolate from the interior of other grids are marked either as being an `interiorBoundaryPoint` and an `interpolationPoint` (using a bitwise ‘or’ in the mask).

mark hole boundaries: For each physical boundary find points on other grids that are near to and inside or outside of the boundary. After this step the holes in the grid will be bounded by a boundary of holes points next to a boundary of interpolation points.

remove exterior points: Mark all remaining hole points. These points can be easily swept out since the hole cutting algorithm ensures that all holes are bounded by interpolation points.

classify (improper) interpolation boundary: The points on the stairstep boundaries and interpolation boundaries are collected into a list. We first try to interpolate these points from other grids using improper interpolation. A point is said to interpolate in an improper way from a grid if it simply lies within the grid. Since all the points in the list lie within in the domain they must interpolate from some other grid or else there is something wrong. See the section on trouble-shooting for examples when this step fails.

classify proper interpolation boundary: We now take the list of (improperly) interpolated points and sort them into one of the following categories:

proper interpolation: A point of a grid interpolates in a proper way from a second grid if the appropriate stencil of points exists on the second grid and consists of the correct types of points for the implicit or explicit interpolation.

discretization point: An interpolation point on a physical boundary may be used as a discretization point.

At the successful completion of this step we should have a valid overlapping grid. There should be no fatal errors in performing the final steps.

interpolate discretization points: To reduce the amount of overlap we attempt to interpolate discretization points from grids of higher priority.

remove redundant interpolation points: Any interpolation points that are not needed are removed from the computation. Interpolation points that are needed but that can just as well be used as discretization points are turned into discretization points.

9.3 Hole cutting algorithm

After checking for interpolation points on boundaries, the next step in the overlapping grid algorithm is to cut holes. This is the most critical step in the algorithm. Each side of a grid that represents a physical boundary is used to cut holes in other grids that overlay the boundary.

Each face on grid g representing a physical boundary is used to cut holes in other grids. We also mark points that can interpolate from grid g . The goal is to build a barrier of hole points next to interpolation points that partitions the grid into two regions – one region that is inside the domain and one region that is outside the domain.

- We check for points, \mathbf{x}_g on the face of grid g that can interpolate from from another grid g_2 . These points \mathbf{i}_2 on g_2 are potential hole points.
- A potential hole point is not cut if it can interpolate from grid g , in this case the point is marked as an interpolation point.

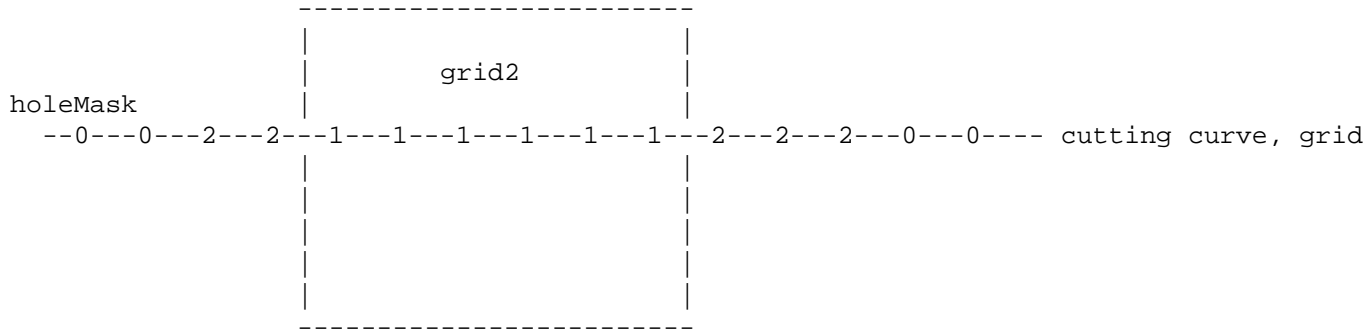
- A potential hole point is NOT cut if the distance to the cutting surface is greater than $2\Delta x_2$ where Δx is a measure of the cell size on g_2 (currently the length of the diagonal of the cell i_2). Thus in general there will be a layer of 1-3 points cut near the cutting surface.
- A potential hole point is NOT cut if the point i_2 already can interpolate from another grid g_3 AND the grid g_3 shares the same boundary with grid g . This condition applies to a thin body and prevents points from being cut that are actually inside the domain on the opposite side of the thin body.

This section needs to be completed...

1. Invert the points \mathbf{x}_g on grid g_2 given coordinates \mathbf{r}_{g_2} .
2. Compute the holeMask mask array which indicates whether a point on the cutting face is inside of outside g_2

Compute the holeMask:

```
holeMask(i1,i2,i3) = 0 : point is outside and not invertible
                   = 1 : point is inside
                   = 2 : point is outside but invertible
```



3. The idea now is to mark all points on g_2 that are near the cutting face.

9.4 Finding exterior points by ray tracing

*** Ray tracing is NO longer performed to remove holes points*** but it is used to generate embedded boundary grids (a future feature).

Exterior points are found by counting the number of times that a semi-infinite ray, starting from a point \mathbf{x} and extending in the y-direction to $+\infty$, crosses the boundaries of the region. If the ray crosses the boundaries an even number of times then it is outside the domain.

If a ray crosses the region where two grids overlap then there will appear to be two points of crossing. We must eliminate one of these points of crossing or else we will obtain an incorrect result.

The ray casting algorithm will determine the intersection of the ray with the boundary surfaces represented as a triangulation of the discrete points.

We keep a list of the positions of intersection, \mathbf{x}_i , as well as the grid and grid point location of the intersection. Ideally we would only need to check whether two points of intersection from two different grids are close, $\|\mathbf{x}_i - \mathbf{x}_j\| < \epsilon$. It is not very easy, however, to determine an appropriate value for ϵ . If the ray crosses the boundary in a nearly normal direction then the distance $d = \|\mathbf{x}_i - \mathbf{x}_j\|$ will be of order the discrepancy between the two discrete representations of the surface which can be estimated by ??

If, however, the ray crosses the boundary in a nearly tangential direction then the distance d could be as large as the grid spacing in the tangential direction.

There are further complications since the body may represent a very thin surface (such as a wing) and there may be points of intersection that are close together in physical space but actually on opposite sides of the thing body.

Thus to perform a robust check we do the following

1. Check that two intersecting points belong to two different grids, $g_1 \neq g_2$.
2. Check that the boundaries on the two grids are shared sides (meaning they belong to the same surface as specified in the grid generation by setting the share flag).

3. Check that the grid cells that contain the points of intersection have some vertices that are interpolation points (so that we know we are in a region of overlap) ???
4. check that the normals to the boundary at the points of intersection point in the same basic direction, $\mathbf{n}_1 \cdot \mathbf{n}_2 > 0$.
5. check that the distance $d = \|\mathbf{x}_i - \mathbf{x}_j\|$ between the points satisfies

$$\alpha = |(\mathbf{x}_2 - \mathbf{x}_1) \cdot \mathbf{n}| / \|(\mathbf{x}_2 - \mathbf{x}_1)\| \quad 0 \leq \alpha \leq 1$$

$d_n \equiv$ normal discrepancy

$d_t \equiv$ tangential discrepancy

$$d \leq \alpha d_n + (1 - \alpha) d_t$$

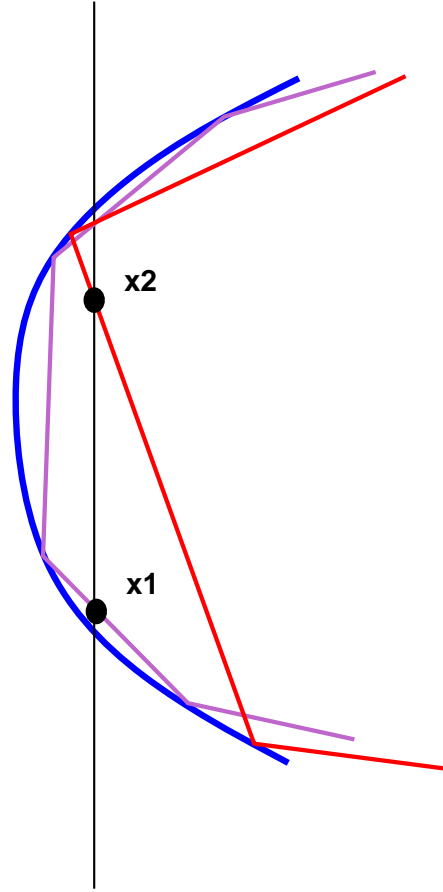


Figure 32: The points of intersection of a ray with a surface covered by two overlapping grids. If the ray is nearly tangent to the surface then the two points of intersection may not be very close together.

9.5 Adjusting grid points for the boundary mismatch problem

When the sides of two grids overlap on a boundary then there can be a problem interpolating one grid from the other if the grids do not match well enough. This problem is especially likely if the grids are formed by interpolating data points and the grid spacing is highly stretched in the normal direction.

Figure (33) shows two grids that share a boundary. If we suppose that the mapping for the grid is defined by linear interpolation between the grid points then it is clear that points on the boundary of grid A appear to be well outside or well inside the boundary of grid B, when actually the boundaries are meant to be the same.

This *boundary mis-match* causes two problems. The first problem, encountered by the grid generator, is that those boundary points (or even interior points for highly stretched grids) that appear to be outside the grid should actually be allowed to interpolate. The hole cutting algorithm will mark these points as being unusable and outside the grid. The second problem occurs in PDE solvers. Even if we allow the points to interpolate, the interpolation will not be very accurate and the solution can look bad.

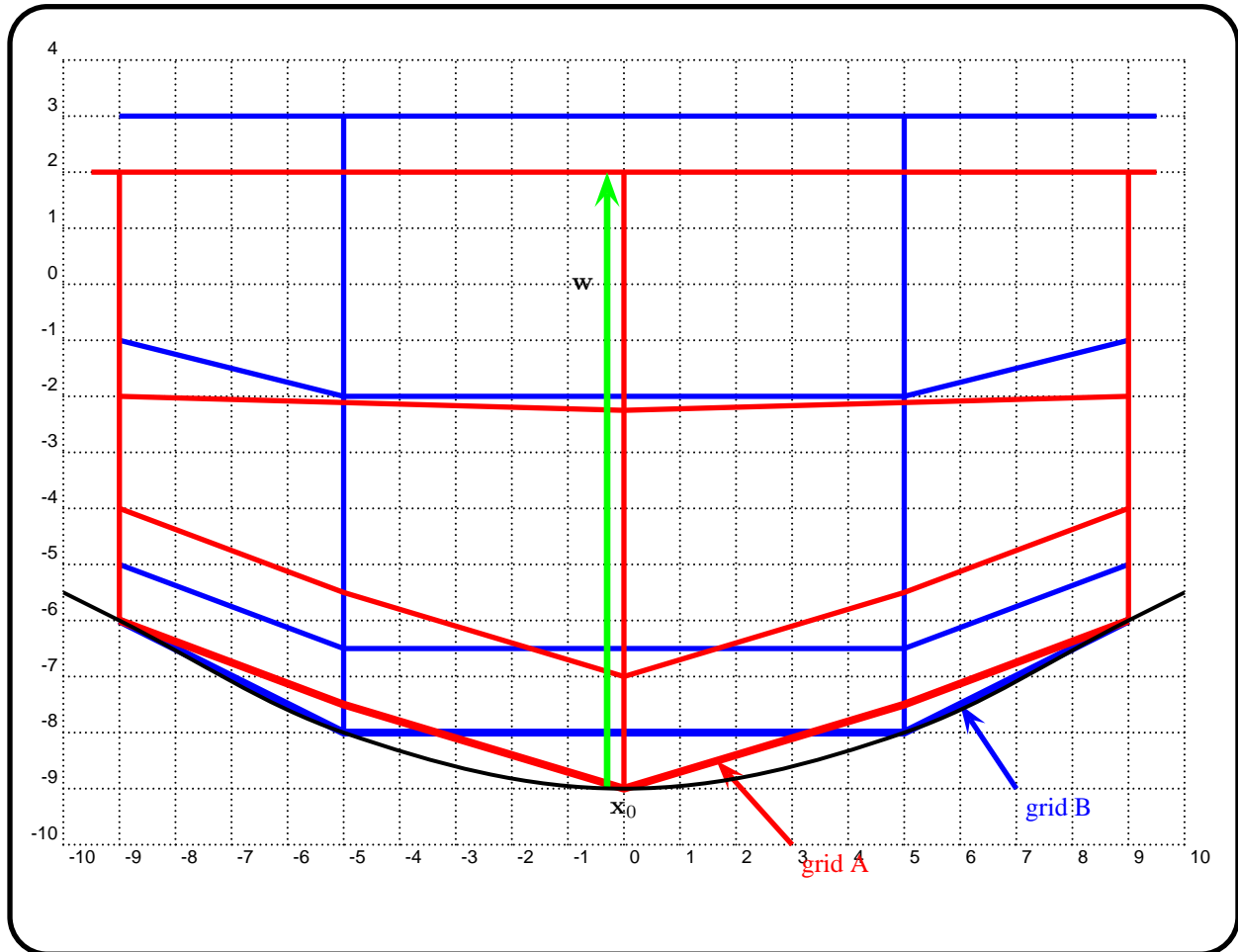


Figure 33: Grid A and Grid B share a boundary but if the mappings are defined by linear interpolation, the grid point x_0 will appear to be outside grid B.

To fix both these problems we adjust the points on grid A so that the boundary points of grid A are shifted to lie exactly on the boundary of grid B. Other points on grid A are also shifted, but the amount of the shift decreases the further we are from the boundary. If the grid is highly stretched then the relative amount we shift the points, compared to the local grid spacing, decreases as we move away from the boundary. For example if the spacing near the boundary is 10^{-3} compared to the spacing away from the boundary layer then the amount we shift interior points will be on the order of 10^{-3} , a very small relative change. **Note that this shift is only done when we are determining the location of A grid points in the parameter space of grid B (for interpolation).** The actual grid points are not changed in the CompositeGrid created by the grid generator. Also note that points on grid A may be shifted one amount when interpolating from grid B, but could be shifted another amount if interpolating from a third grid C.

Referring to figure (34) the point \mathbf{x}_0 is shifted to the point \mathbf{x}_1 on the boundary. The point \mathbf{x}_2 is also shifted, but by a smaller amount, that depends on the distance from the boundary relative to the vector \mathbf{w}

$$\begin{aligned}\tilde{\mathbf{x}}_2 &\leftarrow \mathbf{x}_2 + (\mathbf{x}_1 - \mathbf{x}_0) \left[1 - \frac{(\mathbf{x}_2 - \mathbf{x}_0) \cdot \mathbf{w}}{\|\mathbf{w}\|^2} \right] \\ &\equiv \mathbf{x}_2 + (\mathbf{x}_1 - \mathbf{x}_0) \left[1 - \frac{(\mathbf{x}_2 - \mathbf{x}_0) \cdot \mathbf{w}}{\|\mathbf{w}\|^2} \right] \\ &\equiv \mathbf{S}(\mathbf{x}_1) \mathbf{x}_2\end{aligned}$$

The *opposite-boundary* vector \mathbf{w} is chosen to extend from the boundary to the grid points as some distance from the boundary. We use the grid line that is at least 1/3 of the distance (in index space) to the opposite side, but at least 10 lines (unless there are fewer than 10 lines). The vector should be far enough away so that points in the boundary layer are shifted to be inside the other grid, but close enough so that \mathbf{w} is nearly parallel to the normal to the boundary.

The shift operator \mathbf{S} will project the boundary points of grid A onto the boundary of grid B.

A complication occurs if the more than one side of grid A shares sides with the same grid B, as shown in figure (34). In this case we must determine shifts in multiple directions so that after these shifts the boundary points on grid A are shifted to lie on the boundary of grid B. We cannot simply apply the above algorithm for each side independently.

To fix this problem we sequentially apply the shift operations more than once in order to ensure that the grids points are projected onto all the shared boundaries. Let \mathbf{S}_0 , \mathbf{S}_1 and \mathbf{S}_2 denote the shift mappings in each coordinate direction. In two dimensions, the operator

$$\tilde{\mathbf{x}}_2 \leftarrow \mathbf{S}_1 \mathbf{S}_0 \mathbf{x}$$

will not work properly since after the application of \mathbf{S}_1 the points on boundary 0 can be shifted off the boundary. However the operator

$$\tilde{\mathbf{x}}_2 \leftarrow \mathbf{S}_0 \mathbf{S}_1 \mathbf{S}_0 \mathbf{x}$$

would work since the final \mathbf{S}_0 operator will not change the points on boundary 1 (since the corner points of grid A have been projected to the corner points of grid B after the two steps $\mathbf{S}_1 \mathbf{S}_0 \mathbf{x}$).

Rather than applying \mathbf{S}_0 twice it is more efficient to define new operators to perform the projection in only two steps:

$$\tilde{\mathbf{x}}_2 \leftarrow \tilde{\mathbf{S}}_1 \tilde{\mathbf{S}}_0 \mathbf{x}$$

We can do this

$$\begin{aligned}\tilde{\mathbf{S}}_0 &= \mathbf{S}_0(\mathbf{x}_1 + \mathbf{y}) \\ \mathbf{y} &= \mathbf{S}_0(\mathbf{x}_1) \mathbf{x}_1 \\ \tilde{\mathbf{S}}_1 &= \mathbf{S}_1\end{aligned}$$

In three-dimensions if we have three adjacent shared faces then

$$\begin{aligned}\tilde{\mathbf{x}}_2 &\leftarrow \tilde{\mathbf{S}}_2 \tilde{\mathbf{S}}_1 \tilde{\mathbf{S}}_0 \mathbf{x} \\ \tilde{\mathbf{S}}_0 &= \mathbf{S}_0 \mathbf{S}_2 \mathbf{S}_1 \mathbf{S}_0 \\ \tilde{\mathbf{S}}_1 &= \mathbf{S}_1 \\ \tilde{\mathbf{S}}_2 &= \mathbf{S}_2\end{aligned}$$

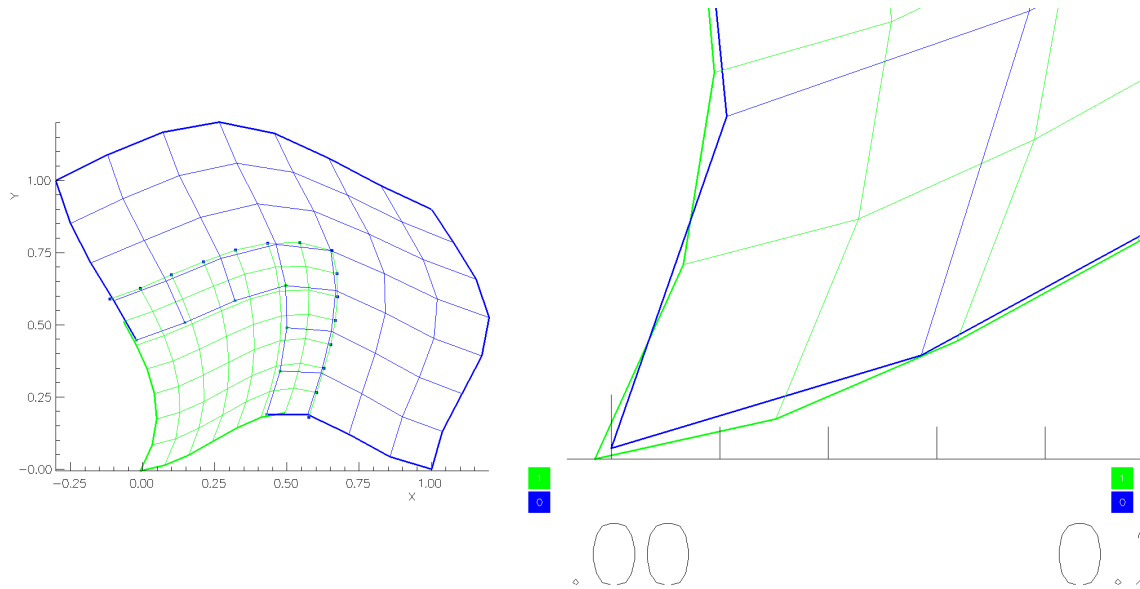


Figure 34: An overlapping grid testing the mismatch problem, created with `mismatch.cmd`. The refinement grid is artificially translated so that the two boundaries it shares with the base grid do not match. The figure on the right is a magnification of the lower left corner, before the overlap algorithm was applied.

9.6 Refinement Grids

Refinement grids can be added to a `GridCollection` or to a `CompositeGrid`. The component grids that exist in the original `CompositeGrid` are known as **base grids**. These grids represent **refinement level 0**. Refinement grids are added on a particular base grid and belong to a particular level. Normally the refinement levels are **properly nested** so that all grids on refinement level l are contained in the grids on refinement level $l - 1$.

A given refinement grid will have only one parent grid on refinement level 0, i.e. it will belong to only one base grid. A refinement grid on level l may have more than one parent grid on level $l - 1$.

Normally a refinement grid will interpolate its ghost values from other refinement grids on the same level or from its parent grids. Points on the parent grid that lie underneath the refinement will interpolate from the refinement (also known as the child grid).

If refinement grids lie in a region where two base grids overlap, it is necessary to determine how the refinements interpolate from the grids they overlap that belong to a different base grid.

The `updateRefinements` function determines how refinement grids interpolate from other grids that they overlap. This function does not determine how a refinement grid interpolates from the grid it has refined.

If a refinement...

9.7 Improved Quality Interpolation

This is new Version 16 or higher.

Normally one wants to avoid having a fine grid interpolate from a coarse grid or vice versa. Often this can be accomplished through the normal specification of a priority for each grid. Sometimes, however, using a single priority per grid is not sufficient.

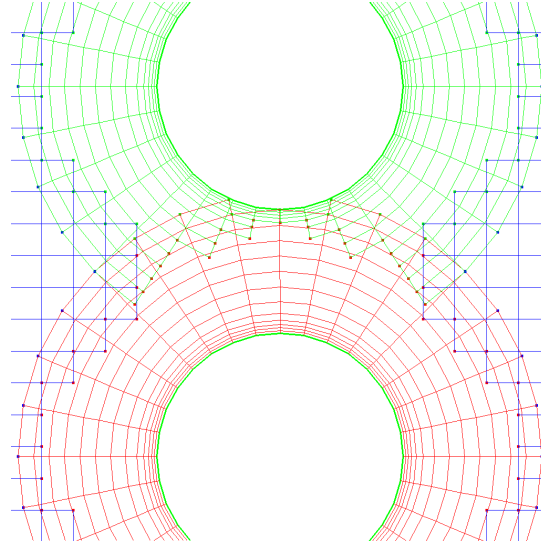


Figure 35: The lower annulus (the highest priority grid) has points that interpolate from the fine boundary layer grid of the upper annulus. This interpolation will be inaccurate if the solution varies rapidly in the boundary layer, and the lower annulus will be unable to represent the boundary layer solution accurately. This problem cannot be fixed by simply changing the priorities of the grids.

Figure (35) shows a grid where the highest priority grid (the bottom annulus) interpolates from the fine boundary layer grid of the top annulus. By turning on the flag to improve the quality of interpolation the grid shown in figure (36) results.

We use a simple measure of the quality of the interpolation to be the relative size of the grid cells on the two grids involved.

$$\text{quality of interpolation} = \frac{\text{cell size of the interpolation point}}{\text{cell size of the interpolatee point}}$$

The quality is bad (i.e. large) if the interpolatee grid cells are smaller. This simple measure seems adequate for our purposes of preventing coarse grid points on higher priority grids from interpolating from lower priority grids.

The **algorithm** for removing poor quality points is

1. Follow the standard algorithm until all points have been interpolated but redundant points have not yet been removed.
2. Try to interpolate all points on the finest grid that can interpolate from a lower priority grid. (This is not done in the standard case).
3. Attempt to remove poor quality points from the *boundary* of the interpolation point region where a point interpolates from a lower priority grid. A point is removed if it is not needed for discretization and the quality measure is greater than a specified value (normally around 2). If a point is removed then also check the new *boundary* points that are now exposed.
4. After points have been removed we need to go back and update any other interpolation points that can no-longer interpolate (since they required some of the points that were deleted).

The algorithm is supposed to be guaranteed to give a valid grid provided a grid could be made without the improvement steps.

9.7.1 Note:

There is a more sophisticated way to measure the quality of interpolation. ***This measure is not used currently**.

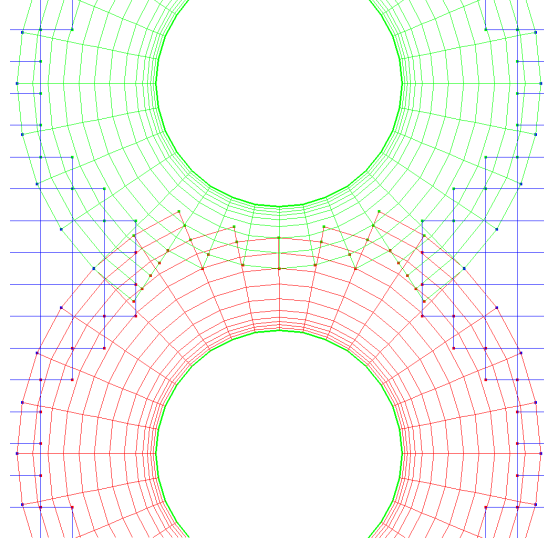


Figure 36: With the ‘improved quality’ option turned on, the lower annulus no longer interpolates from the fine boundary layer of the upper annulus.

One way to measure the quality of the interpolation is defined as follows. We would like the cell at an interpolation point on grid A to be approximately the same size, shape and orientation as the cells on the interpoolee grid B. The vector

$$\mathbf{d}_i^A = \frac{\partial \mathbf{x}^A}{\partial r_i} \Delta r_i^A$$

measures the grid cell spacing and orientation of the side of the cell along the axis r_i of grid A. This vector corresponds to a vector in the parameter space of grid B given by

$$\mathbf{r}_i^B = \left[\frac{\partial \mathbf{r}^B}{\partial \mathbf{x}} \right] \mathbf{d}_i^A$$

The length in grid cells of this vector \mathbf{r}_i^B is approximately

$$\left\| \begin{bmatrix} \frac{1}{\Delta r_1^B} & 0 & 0 \\ 0 & \frac{1}{\Delta r_2^B} & 0 \\ 0 & 0 & \frac{1}{\Delta r_3^B} \end{bmatrix} \mathbf{r}_i^B \right\|$$

where we have scaled each element by the appropriate grid spacing. This length should be near 1 for good quality (since the original vector \mathbf{d}_i^A has a length of one grid cell).

Thus to measure the quality of all sides on the original cell we can compute

$$p = \left\| \begin{bmatrix} \frac{1}{\Delta r_1^B} & 0 & 0 \\ 0 & \frac{1}{\Delta r_2^B} & 0 \\ 0 & 0 & \frac{1}{\Delta r_3^B} \end{bmatrix} \left[\frac{\partial \mathbf{r}^B}{\partial \mathbf{x}} \right] \left[\frac{\partial \mathbf{x}^A}{\partial \mathbf{r}} \right] \begin{bmatrix} \Delta r_1^A & 0 & 0 \\ 0 & \Delta r_2^A & 0 \\ 0 & 0 & \Delta r_3^A \end{bmatrix} \right\|$$

The interpolation will be defined to be of high quality if this norm is near 1. In particular we use the quality measure

$$q = \frac{1}{2} \left(p + \frac{1}{p} \right)$$

where we prefer points with a smaller value for q.

10 Treatment of nearby boundaries and the boundaryDiscretisationWidth

**** new with version 18****

Figure (37) shows the grid generated in the case when two boundaries are very near to one another. The `boundaryDiscretisationWidth` parameter, which is by default 3, indicates that any boundary point that is a discretisation point should have two interior neighbouring points so that a one-sided 3-point scheme could be applied on the boundary. To ensure this condition is satisfied extra points are allowed that normally would not be valid. The interpolation points that are outside the domain are “interpolated” from the nearest point on the boundary by pretending that the interpolation point has been moved to the boundary. This will only be first order accurate interpolation.

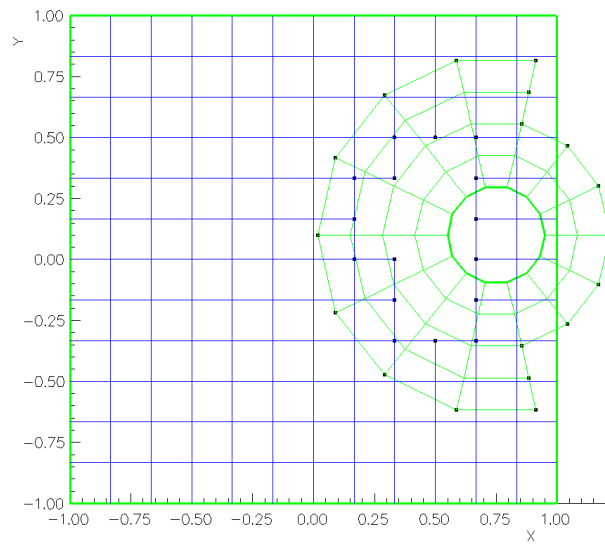


Figure 37: When two boundaries are nearby to one another the overlapping grid algorithm ensures that enough interior grid-points remain next to the boundary points to allow the boundary point to be discretised. While not very accurate this approach at least allows a grid to be built.

11 Adaptive Mesh Refinement

When refinement grids are added to an overlapping grid and a refinement grid overlaps an interpolation boundary, the Ogen function `updateRefinement` should be called. This function will cut holes in the refinement grids and determine how to interpolate points on the hole-boundary.

The order of preference for the interpolation of a point on the hole-boundary of a refinement grid is to

1. interpolate from another refinement at the same level and different base grid
2. interpolate from another refinement at a lower level and different base grid
3. interpolate from a refinement grid on the same base grid (this case should only be used as a backup and should normally not be needed).

11.1 The algorithm for updating refinement meshes added to an overlapping grid.

There are two main steps in the algorithm for adding refinement meshes to an overlapping grid.

1. Build a mask array for each refinement grid that indicates where holes are and which points should be interpolated.
2. For each interpolation point on the hole boundary, find which grid to interpolate from.

To be efficient, these steps are performed with a different procedure than the normal overlapping grid algorithm. The mask array is built entirely by looking at the mask array from the base grids. The interpolation points are determined by looking at the interpolation points on the base grids in order to determine the likely interpolatee grids.

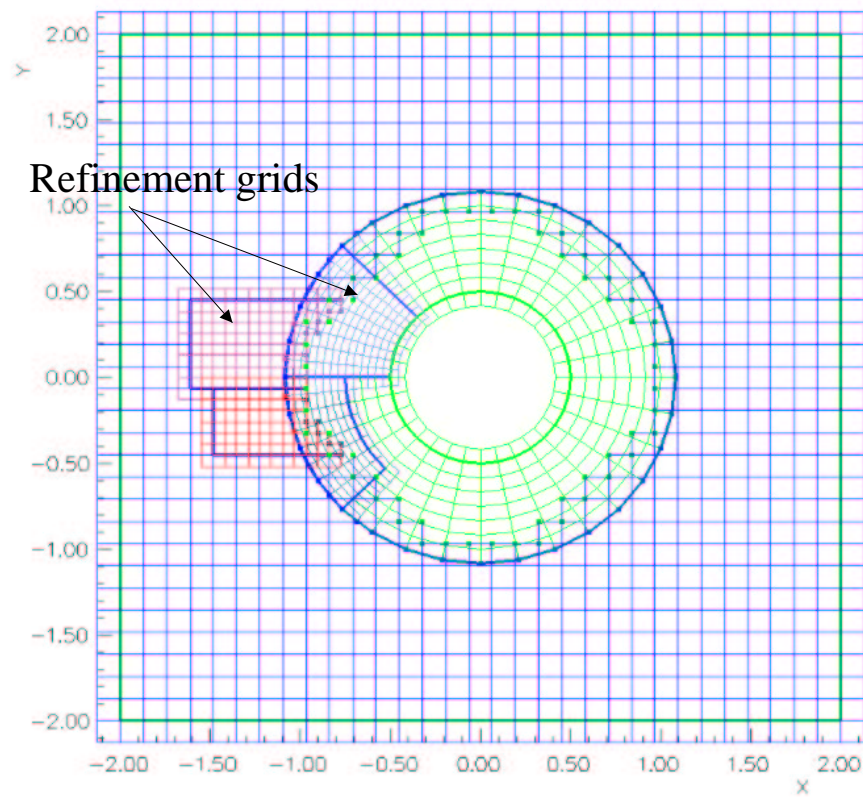
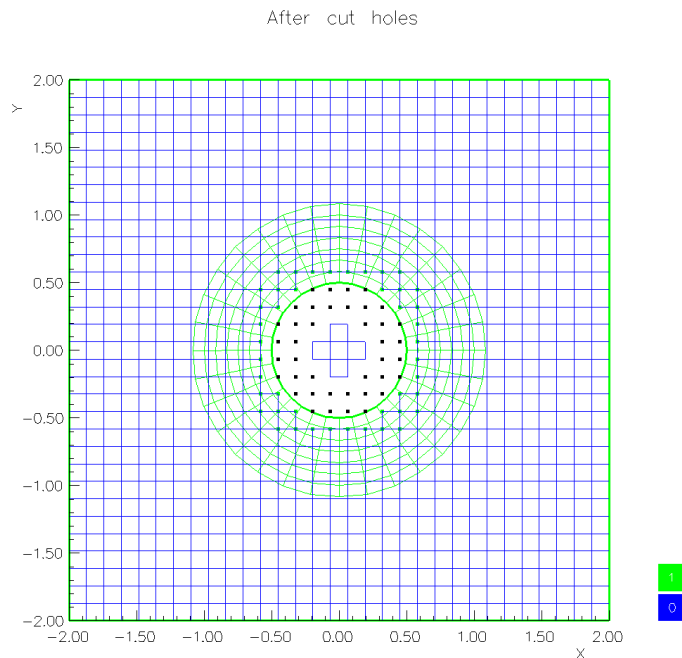


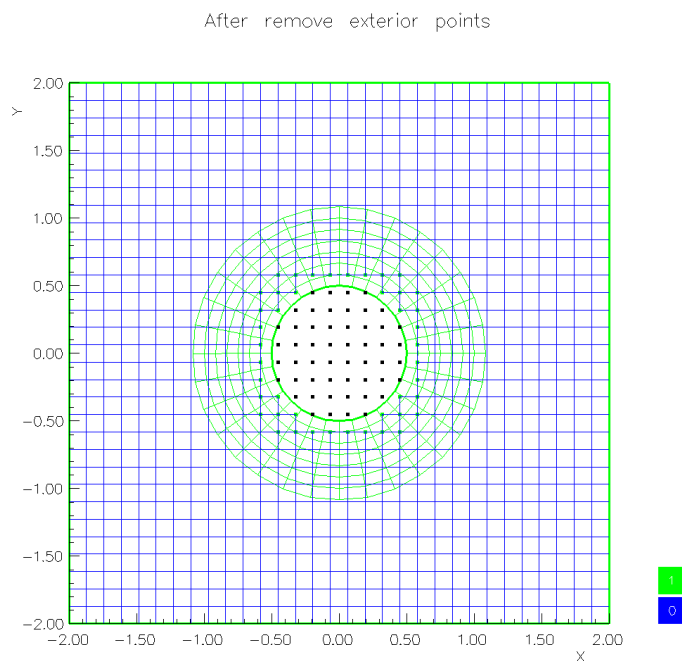
Figure 38: When refinement grids are added to an overlapping grid, the `updateRefinement` function should be called in order to compute a valid grid.

11.2 Example: Circle in a Channel

These figures show the circle in a channel grid at various stages in the overlap algorithm.

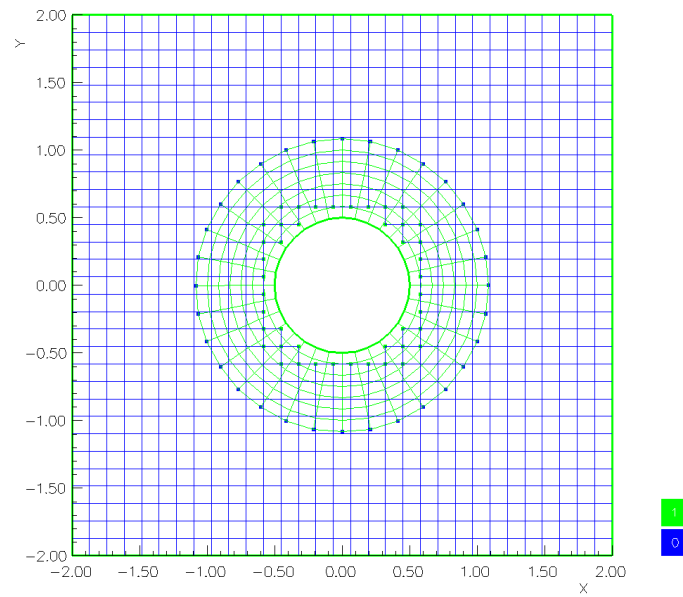


Grid after cutting holes. Physical boundaries are used to cut holes in nearby grids. The hole cutting algorithm will generate a barrier of hole points and interpolation points that bounds the entire hole region.



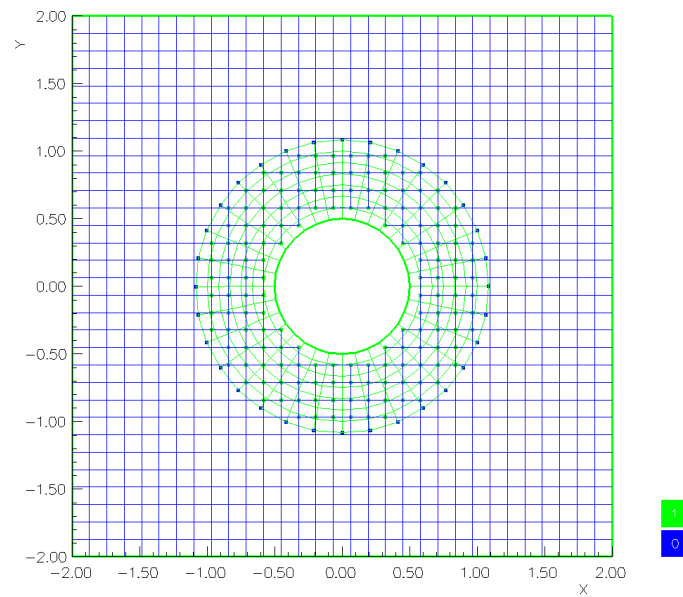
Grid after removing all exterior points. The exterior points are easily swept out after the hole boundary has been marked.

After marking (improper) interpolation

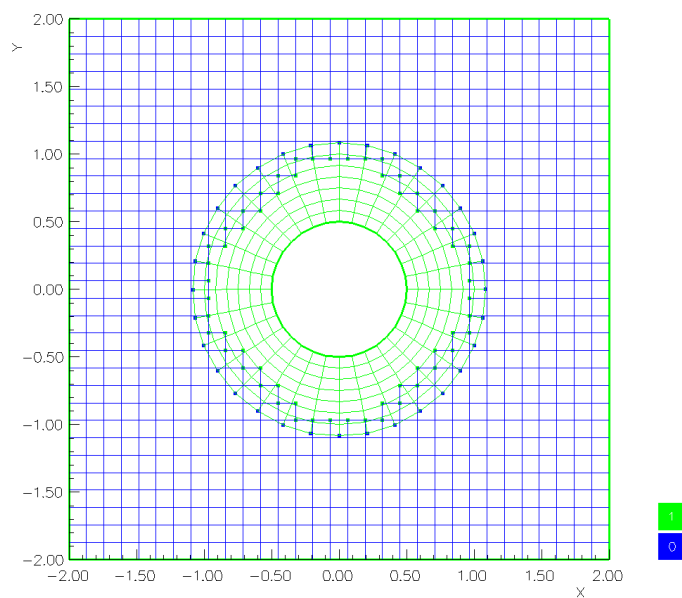


Grid after marking (improper) interpolation. These improper interpolation points need only lie inside another grid.

After marking all interpolation



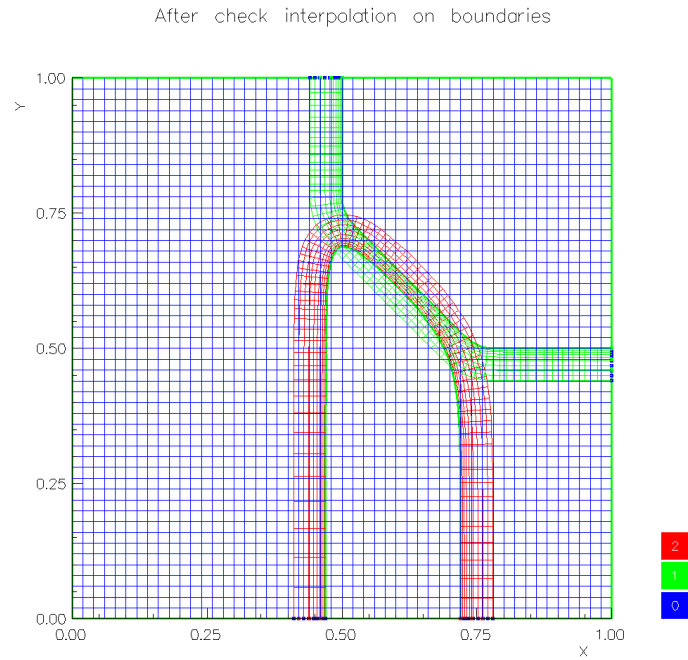
Grid after marking all (proper) interpolation. We have attempted to interpolate discretization points on each grid from grids of higher priority.



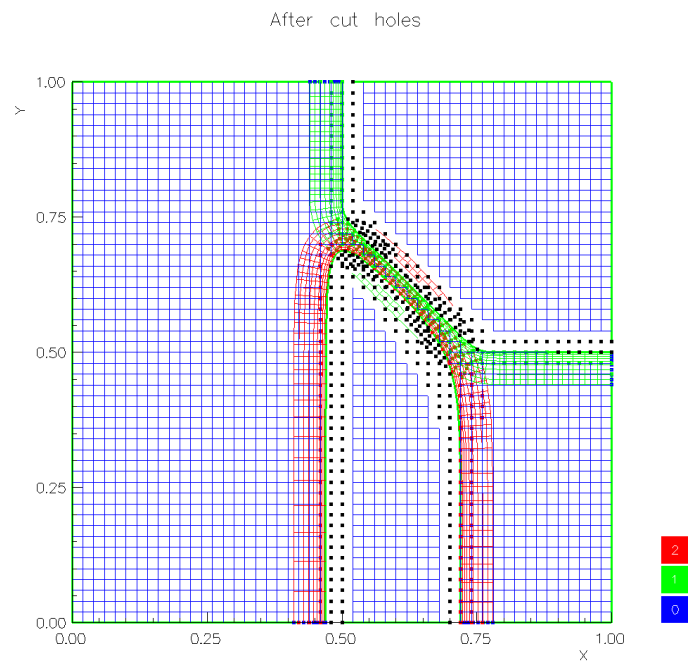
Finished grid after removing excess interpolation points.

11.3 Example: Valve

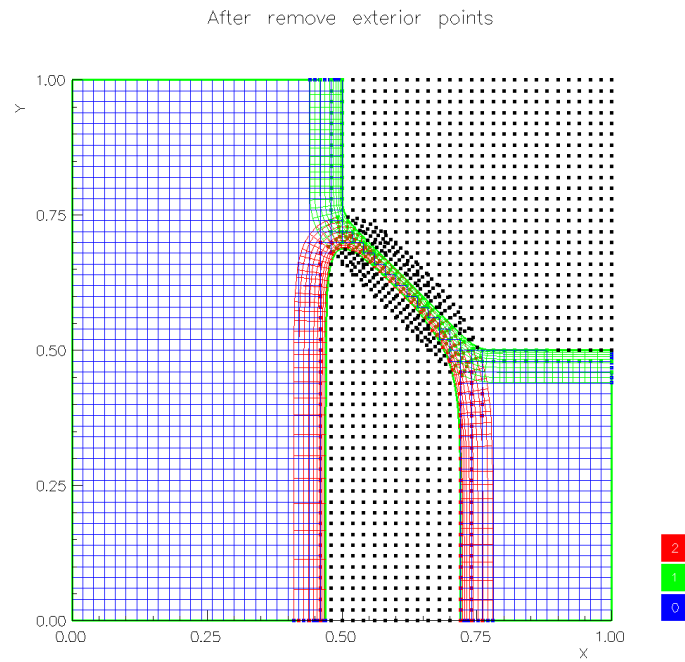
These figures show the grid for a valve at various stages in the overlap algorithm.



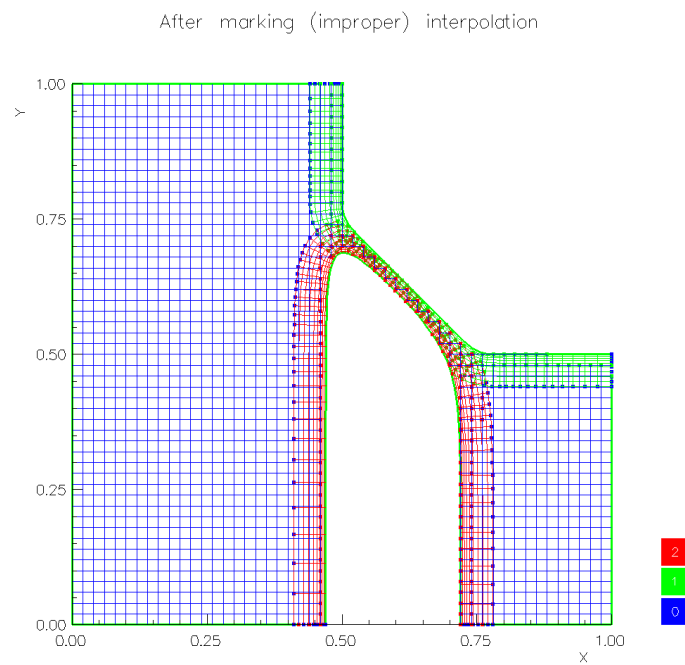
Grid after interpolation on boundaries.



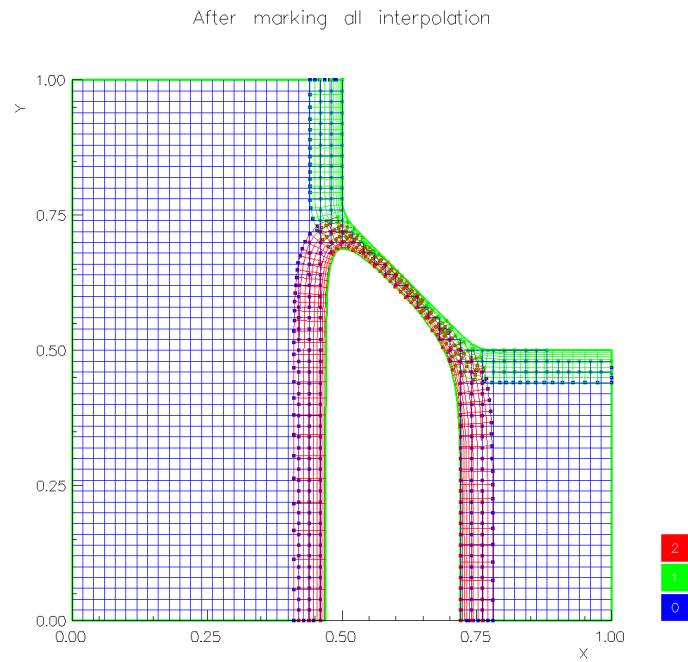
Grid after cutting holes. Physical boundaries are used to cut holes in nearby grids. The hole cutting algorithm will generate a barrier of hole points and interpolation points that bounds the entire hole region.



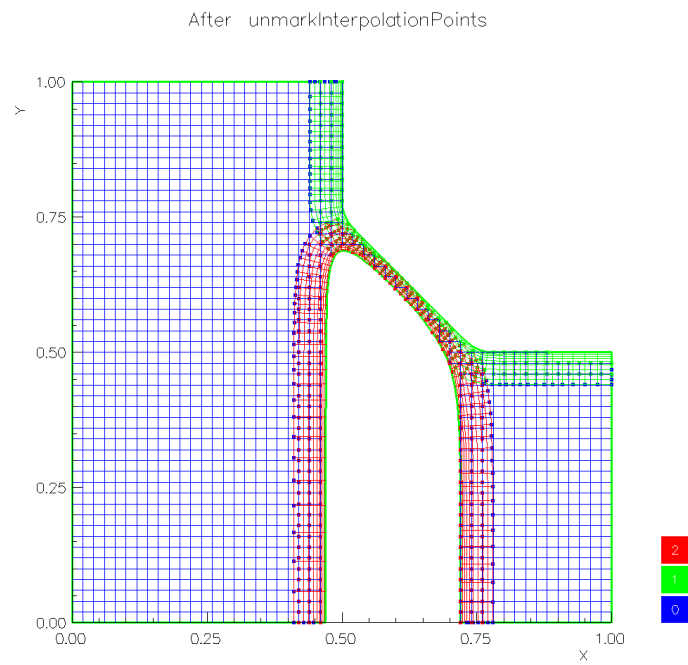
Grid after removing all exterior points. The exterior points are easily swept out after the hole boundary has been marked.



Grid after marking (improper) interpolation. These improper interpolation points need only lie inside another grid.



Grid after marking all (proper) interpolation.



Finished grid after removing excess interpolation points.

References

- [1] G. CHESHIRE AND W. HENSHAW, *Composite overlapping meshes for the solution of partial differential equations*, J. Comp. Phys., 90 (1990), pp. 1–64.
- [2] W. HENSHAW, *Mappings for Overture, a description of the Mapping class and documentation for many useful Mappings*, Research Report LA-UR-96-3469, Los Alamos National Laboratory, 1996.
- [3] ———, *Plotstuff: A class for plotting stuff from Overture*, Research Report LA-UR-96-3893, Los Alamos National Laboratory, 1996.

Index

- adaptive mesh refinement
 - ogen, 69
- airfoil, 21
- body of revolution, 32
- boundary condition, 5
 - mixed boundary condition, 47
 - physical boundary, 5
- boundary mismatch, 62
- boundaryDiscretisationWidth, 67
- building, 46
- c-grid, 47
- command file, 8
- cutting holes
 - turning off, 6
- grid generation, 1
- h-grid, 47
- hints, 52
- hole cutting, 59
 - algorithm, 59
 - manual, 51
 - phantom, 51
- hybrid grid, 23
- interpolation, 6
 - explicit, 6
 - implicit, 6
 - improper, 59
 - improved quality, 65
 - proper, 59
 - redundant, 59
 - turning off, 6
- mapping
 - AirFoilMapping, 21
 - transfinite interpolation, 21
- orthographic, 26
- overlapping grid algorithm, 59
- phantom hole cutting, 51
- refinement grids, 64
- rocket, 46
- share flag, 6
- tips, 54
- trouble shooting, 52
- unstructured grid, 23
- user defined mapping, 55